

Note on Soft Graviton theorem by KLT Relation

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ABSTRACT: Recently, new soft graviton theorem proposed by Cachazo and Strominger has inspired a lot of works. In this note, we use the KLT-formula to investigate the theorem. We have shown how the soft behavior of color ordered Yang-Mills amplitudes can be combined with KLT relation to give the soft behavior of gravity amplitudes. As a byproduct, we find two nontrivial identities of the KLT momentum kernel must hold.

KEYWORDS: Soft graviton theorem, KLT relation.

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1. Introduction

Many scattering amplitudes were shown to have an universal soft behavior when the momentum of an external leg tends to zero. The soft limit can be traced back to the work [1, 2]. In recent years, a new soft theorem for gravity amplitudes was studied in [3, 4, 5]. Using Britto-Cachazo-Feng-Witten (BCFW) recursion [6, 7], Cachazo and Strominger have proved the sub- and subsub- leading orders in the soft expansion [8], i.e.,¹

$$M_{n+1}(\{\epsilon\lambda_s, \tilde{\lambda}_s\}, 1, \dots, n) = \left(\frac{1}{\epsilon^3} S_{GR}^{(0)} + \frac{1}{\epsilon^2} S_{GR}^{(1)} + \frac{1}{\epsilon} S_{GR}^{(2)} \right) M_n(1, \dots, n) + \mathcal{O}(\epsilon^0). \quad \text{[Gra-soft-form](1.1)}$$

¹The leading soft factor $S_{GR}^{(0)}$ is not corrected to all loop orders is shown in [2, 9] while the general subleading behavior of soft gluons and gravitons has also been discussed in [10].

The leading, subleading and subsubleading orders of soft factors are given by

$$S_{GR}^{(0)} = \sum_{a=1}^n \frac{\varepsilon_{\mu\nu}^s p_a^\mu p_a^\nu}{p_s \cdot p_a}, \quad S_{GR}^{(1)} = \sum_{a=1}^n \frac{\varepsilon_{\mu\nu}^s p_a^\mu (p_{s,\rho} J_a^{\rho\nu})}{p_s \cdot p_a}, \quad S_{GR}^{(2)} = \frac{1}{2} \sum_{a=1}^n \frac{\varepsilon_{\mu\nu}^s (p_{s,\rho} J_a^{\rho\mu})(p_{s,\sigma} J_a^{\sigma\nu})}{p_s \cdot p_a}, \quad [\text{CS-}\epsilon\text{-T}^2]$$

where the $\varepsilon_{\mu\nu}^s$ is the polarization of the soft graviton, p_i are external momenta and $J^{\mu\nu}$ are angular momenta of external legs. Using the BCFW recursion relation, the soft limit of color-ordered tree-level Yang-Mills amplitudes was also studied in [11] and the result is given by

$$A_{n+1}(\{\epsilon\lambda_s, \tilde{\lambda}_s\}, 1, \dots, n) = \left(\frac{1}{\epsilon^2} S_{YM}^{(0)} + \frac{1}{\epsilon} S_{YM}^{(1)} \right) A_n(1, \dots, n), \quad [\text{YM-soft-form}] \quad (1.3)$$

where the leading and subleading soft factors are given by

$$S_{YM}^{(0)} = \sum_{a \sim s} \frac{\varepsilon_s \cdot p_a}{p_s \cdot p_a}, \quad S_{YM}^{(1)} = \sum_{a \sim s} \frac{\varepsilon_{sv} p_{s\mu} J_a^{\mu\nu}}{p_s \cdot p_a}, \quad [\text{YM-conj}] \quad (1.4)$$

with ε_{sv} denoting the polarization of the soft gluon and $a \sim s$ meaning partial a is next to soft particle s . Many related studies have been achieved including the soft limits from Poincare symmetry and gauge invariance [12, 13], Feynman diagram approach [14], conformal symmetry approach to the soft limits in Yang-Mills theory [15], the soft limit in arbitrary dimension [16, 17, 18, 19], loop correction of the soft limit [20, 21, 22, 24], string-theory approach to the soft limit [23, 24] and ambitwistor string approach [25, 26].

In physics, it is very fruitful to study same thing from various angles because it will deepen our understanding and reveal many hidden relations. Now on-shell graviton scattering amplitudes can be calculated using many different ways, such as BCFW recursion relation, the double-copy formula [27], CHY formula [28, 29] and KLT formula [30] (and many more). Since the BCFW recursion relation and CHY formula have been successfully used in the study, in this note we will try to use the KLT formula to investigate the new soft graviton theorem.

Gravity amplitudes at tree level satisfy the famous Kawai-Lewellen-Tye (KLT) relation [30], with which, one can express the **stripped** tree-level gravity amplitudes M_n (i.e., the momentum conservation $\delta^4(\sum p_i)$ has been moved away) in terms of products of tree-level color-ordered **stripped** Yang-Mills amplitudes A_n and \tilde{A}_n

$$M_n(1, 2, \dots, n) = \sum_{\sigma, \rho} A_n(\sigma) \mathcal{S}[\sigma|\rho] \tilde{A}_n(\rho), \quad [\text{KLT}] \quad (1.5)$$

where $\mathcal{S}[\sigma|\rho]$ is called **momentum kernel**, which is a function of kinematic factors $s_{ij} = 2p_i \cdot p_j$ and depends on the permutations σ and ρ^2 . KLT relation was firstly proposed in string theory [30] and then was proved in field theory [31, 32] using BCFW recursion. One important feature should be emphasized is that KLT is relation between stripped amplitudes without imposing momentum conservation delta function.

Since KLT relation (1.5) connects gravity amplitudes to Yang-Mills amplitudes, it is natural to expect that the soft limit of gravity amplitudes can be derived from that of Yang-Mills amplitudes via KLT

²In fact, the momentum kernel can be treated as the metric on the space of $(n-3)!$ BCJ basis.

relation. In this work, we investigate this connection and its consequences. Although the KLT relation holds to general dimension, for simplicity we will focus on the pure 4D. We will show how the leading and sub-leading soft factors of gravity amplitudes can be reproduced by the leading and sub-leading soft factors of Yang-Mills amplitudes as it should be. However, to reach such now well established fact, some nontrivial relations among changing matrix of $(n-3)!$ BCJ-basis and momentum kernel $\mathcal{S}[\rho|\sigma]$ must be true. These nontrivial hidden identities are one of our main results.

The structure of this paper is following. In section 2, we provide a brief review of KLT relation. In section 3, we recall the soft limit for stripped amplitudes of gravity and Yang-Mills theory. In section 4, using results in section 3, we present the frame of the proof of the soft graviton soft theorem via KLT relation. In section 5, two examples have been given to demonstrate the frame in section 4. In section 6, we summarize our work with some future directions. In appendix A, we present another more complicated example.

2. A review of KLT relation

In this section, we provide a brief review of various formulations of KLT relation for gravity amplitudes (for more details, please refer [31, 32]). The most general formula [9] is given as

$$M_n(1, 2, \dots, n) = (-1)^{n+1} \sum_{\sigma \in S_{n-3}} \sum_{\alpha \in S_{j-1}} \sum_{\beta \in S_{n-2-j}} A_n(1, \sigma_{2,j}, \sigma_{j+1, n-2}, n-1, n) \mathcal{S}[\alpha_{\sigma(2), \sigma(j)} | \sigma_{2,j}]_{p_1} \\ \times \mathcal{S}[\sigma_{j+1, n-2} | \beta_{\sigma(j+1), \sigma(n-2)}]_{p_{n-1}} \tilde{A}_n(\alpha_{\sigma(2), \sigma(j)}, 1, n-1, \beta_{\sigma(j+1), \sigma(n-2)}, n), \quad [\text{KLT-ber}] \quad (2.1)$$

where A and \tilde{A} are two copies of color-ordered Yang-Mills amplitudes and the momentum kernel [31, 32, 33] is defined as

$$\mathcal{S}[i_1, i_2, \dots, i_k | j_1, j_2, \dots, j_k]_{p_1} = \prod_{t=1}^k (s_{i_t} + \sum_{q>t}^k \theta(i_t, i_q) s_{i_t i_q}) \quad [\text{S-def}] \quad (2.2)$$

where p_1 is the pivot and $\theta(i_t, i_q)$ is zero when pair (i_t, i_q) has same ordering at both set $\mathcal{I} = \{i_1, i_2, \dots, i_k\}$, $\mathcal{J} = \{j_1, j_2, \dots, j_k\}$, otherwise it is one³. In this definition, the set $\mathcal{J} = \{j_1, j_2, \dots, j_k\}$ is the reference ordering set, i.e., this set provides the standard ordering. The set $\mathcal{I} = \{i_1, i_2, \dots, i_k\}$ is the dynamical set which determines the dynamical factor by comparing with set \mathcal{J} . A few examples are the following:

$$\mathcal{S}[2, 3, 4 | 2, 4, 3]_{p_1} = s_{21}(s_{31} + s_{34})s_{41}, \quad \mathcal{S}[2, 3, 4 | 4, 3, 2]_{p_1} = (s_{21} + s_{23} + s_{24})(s_{31} + s_{34})s_{41}.$$

Although it is not so obvious, the momentum kernel, in fact, contains all BCJ-relations by following identities

$$0 = \sum_{\alpha \in S_{n-2}} \mathcal{S}[\alpha(i_2, \dots, i_{n-1}) | j_2, j_3, \dots, j_{n-2}] A_n(n, \alpha(i_2, \dots, i_{n-1}), 1), \forall j \in S_{n-2} \quad [\text{I-com}] \quad (2.3)$$

³The function \mathcal{S} is nothing, but the f -function defined in [9] with more symmetric and improved expression

Using (2.3) we can derive following relation

$$\begin{aligned} & \sum_{\alpha, \beta} \mathcal{S}[\alpha_{i_2, i_j} | i_2, \dots, i_j]_{p_1} \mathcal{S}[i_{j+1}, \dots, i_{n-2} | \beta_{i_{j+1}, i_{n-2}}]_{p_{n-1}} \tilde{A}_n(\alpha_{i_2, i_j}, 1, n-1, \beta_{i_{j+1}, i_{n-2}}, n) \\ &= \sum_{\alpha', \beta'} \mathcal{S}[\alpha'_{i_2, i_{j-1}} | i_2, \dots, i_{j-1}]_{p_1} \mathcal{S}[i_j, i_{j+1}, \dots, i_{n-2} | \beta'_{i_j, i_{n-2}}]_{p_{n-1}} \tilde{A}_n(\alpha'_{i_2, i_{j-1}}, 1, n-1, \beta'_{i_j, i_{n-2}}, n), \end{aligned} \quad [2.4]$$

Thus we can shift j in (2.1) all the way to make the left- or right-hand part empty, *i.e.* we can choose $j = 1$ or $j = n - 2$. These special cases corresponds to the manifest S_{n-3} -symmetric form (2.5) and its dual form (2.6), which are given by

$$M_n(1, \dots, n) = (-)^{n+1} \sum_{\sigma, \tilde{\sigma} \in S_{n-3}} A_n(1, \sigma_{2, n-2}, n-1, n) \mathcal{S}[\tilde{\sigma}_{2, n-2} | \sigma_{2, n-2}]_{p_1} \tilde{A}_n(n-1, n, \tilde{\sigma}_{2, n-2}, 1). \quad [KLT-grav]$$

and

$$M_n(1, \dots, n) = (-1)^{n+1} \sum_{\sigma, \tilde{\sigma} \in S_{n-3}} A_n(1, \sigma_{2, n-2}, n-1, n) \mathcal{S}[\sigma_{2, n-2} | \tilde{\sigma}_{2, n-2}]_{p_{n-1}} \tilde{A}_n(1, n-1, \tilde{\sigma}_{2, n-2}, n). \quad [dual-KLT-grav]$$

3. Review of soft limits of gravity and Yang-Mills theory

In this section, we review the soft behavior of gravity and Yang-Mills theory given in [11, 8]. Since in KLT formula, amplitudes used are these **stripped** amplitudes, thus we will focus on the soft behaviors of these amplitudes.

We focus on the four dimensional case, thus we can use spinor variables. Under these variables, soft factors in (1.2) and (1.4) are given by [8] for gravity theory⁴

$$\begin{aligned} S_{GR}^{(0)} &= - \sum_{i=1}^n \frac{[s|i] \langle x|i \rangle \langle y|i \rangle}{\langle s|i \rangle \langle x|s \rangle \langle y|s \rangle}, & S_{GR}^{(1)} &= - \frac{1}{2} \sum_{i=1}^n \frac{[s|i]}{\langle s|i \rangle} \left(\frac{\langle x|i \rangle}{\langle x|s \rangle} + \frac{\langle y|i \rangle}{\langle y|s \rangle} \right) \tilde{\lambda}_s^{\dot{\alpha}} \frac{\partial}{\partial \tilde{\lambda}_i^{\dot{\alpha}}} \\ S_{GR}^{(2)} &= - \frac{1}{2} \sum_{i=1}^n \frac{[s|i]}{\langle s|i \rangle} \tilde{\lambda}_s^{\dot{\alpha}} \tilde{\lambda}_s^{\dot{\beta}} \frac{\partial^2}{\partial \tilde{\lambda}_i^{\dot{\alpha}} \partial \tilde{\lambda}_i^{\dot{\beta}}}, \end{aligned} \quad [CS-conj-4D] \quad (3.1)$$

where x, y are two auxiliary spinors used to define the helicity of soft graviton

$$\epsilon^{+2} = \left(\frac{\lambda_x \tilde{\lambda}_k}{\langle x|k \rangle} \right) \left(\frac{\lambda_y \tilde{\lambda}_k}{\langle y|k \rangle} \right) + \{x \leftrightarrow y\}, \quad (3.2)$$

and by [11] for Yang-Mills theory⁵

$$S_{YM}^{(0)}(n, s, 1, \dots) = \frac{\langle n|1 \rangle}{\langle n|s \rangle \langle s|1 \rangle}, \quad S_{YM}^{(1)}(n, s, 1, \dots) = \frac{1}{\langle s|1 \rangle} \tilde{\lambda}_s \frac{\partial}{\partial \tilde{\lambda}_1} + \frac{1}{\langle n|s \rangle} \tilde{\lambda}_s \frac{\partial}{\partial \tilde{\lambda}_n}. \quad [My-soft-gluon-grav] \quad (3.3)$$

⁴It is worth to emphasize that here we have used the QCD convention, *i.e.*, $2p \cdot q = \langle p|q \rangle [q|p]$.

⁵We have assumed the color ordering is $(1, \dots, n, s)$.

To reach these expressions, we have used the fact that in 4D, angular momentum can be written as spinor form

$$J_{\mu\nu} \rightarrow J_{\alpha\beta}\epsilon_{\dot{\alpha}\dot{\beta}} + \tilde{J}_{\dot{\alpha}\dot{\beta}}\epsilon_{\alpha\beta}, \quad J_{\alpha\beta} = \lambda_\alpha \frac{\partial}{\partial \lambda^\beta} + \lambda_\beta \frac{\partial}{\partial \lambda^\alpha}, \quad \tilde{J}_{\dot{\alpha}\dot{\beta}} = \tilde{\lambda}_{\dot{\alpha}} \frac{\partial}{\partial \tilde{\lambda}^{\dot{\beta}}} + \tilde{\lambda}_{\dot{\beta}} \frac{\partial}{\partial \tilde{\lambda}^{\dot{\alpha}}}. \quad [\text{Angular-4D}] \quad (3.4)$$

We will explain the meaning of differential operators for stripped amplitudes shortly.

For stripped amplitudes, we must impose momentum conservation from beginning. This can be done as given in [8]. Under the **holomorphic soft limit** which is defined as

$$\lambda_s \rightarrow \epsilon \lambda_s, \quad \tilde{\lambda}_s \rightarrow \tilde{\lambda}_s \quad [\text{kin-soft-2}] \quad (3.5)$$

momentum conservation $\sum_{i=1}^n k_i + \epsilon k_s = 0$ can be used to solve two arbitrarily chosen anti-spinors $\tilde{\lambda}_i, \tilde{\lambda}_j$ as

$$\tilde{\lambda}_i = - \sum_{k \neq i, j} \frac{\langle j|k \rangle}{\langle j|i \rangle} \tilde{\lambda}_k - \epsilon \frac{\langle j|s \rangle}{\langle j|i \rangle} \tilde{\lambda}_s, \quad \tilde{\lambda}_j = - \sum_{k \neq i, j} \frac{\langle i|k \rangle}{\langle i|j \rangle} \tilde{\lambda}_k - \epsilon \frac{\langle i|s \rangle}{\langle i|j \rangle} \tilde{\lambda}_s \quad [\text{kin-soft-3}] \quad (3.6)$$

In other words, for stripped amplitudes, now the independent variables are λ_i ($i = 1, \dots, n$), $\lambda_s, \tilde{\lambda}_s$ and $\tilde{\lambda}_k$ ($k = 1, \dots, n$ and $k \neq i, j$). With the fixed choice of pair (i, j) , when we use the BCFW recursion relation to discuss the soft behavior as was done in [21], for example, for an $(n+1)$ -point color-ordered Yang-Mills amplitude $A(\{\epsilon \lambda_s, \tilde{\lambda}_s\}, \{\lambda_1, \tilde{\lambda}_1\}, \dots, \{\lambda_n, \tilde{\lambda}_n\})$ with $h_s = +1$, we will receive contributions to the singular part from the two-particle channel

$$A_{n+1} \left(\{\epsilon \lambda_s, \tilde{\lambda}_s\}^+, 1, \dots, n \right) |_{div} = A_3 \left(\hat{s}^+, 1^{h_1}, -\hat{P}_{1s}^{-h_i} \right) \frac{1}{P_{1s}^2} A_n \left(\hat{P}_{1s}^{h_i}, \dots, \hat{n} \right) |_{div} \quad [\text{soft-div-11}] \quad (3.7)$$

under the (s, n) -shift

$$\epsilon \lambda_s(z) = \epsilon \lambda_s + z \lambda_n, \quad \tilde{\lambda}_n(z) = \tilde{\lambda}_n - z \tilde{\lambda}_s. \quad [\text{soft-def}] \quad (3.8)$$

It is easy to calculate the divergent part and we find

$$\frac{-\langle n|1 \rangle}{\epsilon^2 \langle n|s \rangle \langle s|1 \rangle} A_n \left(\{\tilde{\lambda}_1, \tilde{\lambda}_1 + \epsilon \frac{\langle n|s \rangle}{\langle n|1 \rangle} \tilde{\lambda}_s\}^{h_1}, \dots, \{\lambda_i, \tilde{\lambda}_i(\epsilon)\}, \dots, \{\lambda_j, \tilde{\lambda}_j(\epsilon)\}, \dots, \{\lambda_n, \tilde{\lambda}_n + \epsilon \frac{\langle 1|s \rangle}{\langle 1|n \rangle} \tilde{\lambda}_s\} \right) \quad (3.9)$$

where (3.6) must be used. A compact way to rewrite above expression is to assume $\tilde{\lambda}_i, \tilde{\lambda}_j$ to be independent first, so we have

$$\frac{-\langle n|1 \rangle}{\epsilon^2 \langle n|s \rangle \langle s|1 \rangle} \left\{ \mathbf{e}^{\epsilon \frac{\langle n|s \rangle}{\langle n|1 \rangle} \tilde{\lambda}_s \frac{\partial}{\partial \lambda_1} - \epsilon \frac{\langle j|s \rangle}{\langle j|i \rangle} \tilde{\lambda}_s \frac{\partial}{\partial \lambda_i} - \epsilon \frac{\langle i|s \rangle}{\langle i|j \rangle} \tilde{\lambda}_s \frac{\partial}{\partial \lambda_j} + \frac{\epsilon \langle 1|s \rangle}{\langle 1|n \rangle} \tilde{\lambda}_s \frac{\partial}{\partial \lambda_n}} A_n \left(\{\lambda_1, \tilde{\lambda}_1\}, \dots, \{\lambda_j, \tilde{\lambda}_j\}, \dots, \{\lambda_n, \tilde{\lambda}_n\} \right) \right\} \quad [\text{soft-div-13-4}] \quad (3.10)$$

Only after the action of $\frac{\partial}{\partial \lambda_i}$ and $\frac{\partial}{\partial \lambda_j}$, we can replace $\tilde{\lambda}_i, \tilde{\lambda}_j$ by (3.6) with $\epsilon = 0$. However, if we insist to use (3.6) from beginning, $\tilde{\lambda}_i, \tilde{\lambda}_j$ will depend on $\tilde{\lambda}_1, \tilde{\lambda}_n$ thus the total derivative of $\frac{d}{d\lambda_1}$ and $\frac{d}{d\lambda_n}$ must be written as

$$\frac{d}{d\tilde{\lambda}_1} = \frac{\partial}{\partial \tilde{\lambda}_1} + \frac{\partial}{\partial \tilde{\lambda}_i} \left(-\frac{\langle j|1 \rangle}{\langle j|i \rangle} \right) + \frac{\partial}{\partial \tilde{\lambda}_j} \left(-\frac{\langle i|1 \rangle}{\langle i|j \rangle} \right)$$

$$\frac{d}{d\tilde{\lambda}_n} = \frac{\partial}{\partial\tilde{\lambda}_n} + \frac{\partial}{\partial\tilde{\lambda}_i} \left(-\frac{\langle j|n\rangle}{\langle j|i\rangle} \right) + \frac{\partial}{\partial\tilde{\lambda}_j} \left(-\frac{\langle i|n\rangle}{\langle i|j\rangle} \right). \quad [\text{total-wla1n}] \quad (3.11)$$

Using above formula, it is easy to check that

$$\frac{\langle n|s\rangle}{\langle n|1\rangle} \tilde{\lambda}_s \frac{d}{d\tilde{\lambda}_1} + \frac{\langle 1|s\rangle}{\langle 1|n\rangle} \tilde{\lambda}_s \frac{d}{d\tilde{\lambda}_n} = \frac{\langle n|s\rangle}{\langle n|1\rangle} \tilde{\lambda}_s \frac{\partial}{\partial\tilde{\lambda}_1} + \frac{\langle 1|s\rangle}{\langle 1|n\rangle} \tilde{\lambda}_s \frac{\partial}{\partial\tilde{\lambda}_n} - \frac{\langle j|s\rangle}{\langle j|i\rangle} \tilde{\lambda}_s \frac{\partial}{\partial\tilde{\lambda}_i} - \frac{\langle i|s\rangle}{\langle i|j\rangle} \tilde{\lambda}_s \frac{\partial}{\partial\tilde{\lambda}_j}, \quad (3.12)$$

thus (3.10) becomes

$$\frac{-\langle n|1\rangle}{\epsilon^2 \langle n|s\rangle \langle s|1\rangle} \left\{ e^{\frac{\langle n|s\rangle}{\langle n|1\rangle} \tilde{\lambda}_s \frac{d}{d\tilde{\lambda}_1} + \frac{\langle 1|s\rangle}{\langle 1|n\rangle} \tilde{\lambda}_s \frac{d}{d\tilde{\lambda}_n}} A_n \left(\{\lambda_1, \tilde{\lambda}_1\}, \dots, \{\lambda_j, \tilde{\lambda}_j\}, \dots, \{\lambda_n, \tilde{\lambda}_n\} \right) \right\} \quad [\text{soft-div-13-6}] \quad (3.13)$$

Having this new understanding, the meaning of soft factors in (3.1) and (3.3) becomes clear: *while there are no variables $\tilde{\lambda}_i, \tilde{\lambda}_j$ anymore in stripped amplitudes, all partial derivatives should be considered as a kind of "total derivative" in the sense of (3.11).*

4. KLT relation approach to the soft behavior of gravity amplitude

Having above preparations, now we study the soft behavior of stripped gravity amplitudes using the soft behavior of stripped Yang-Mills amplitudes as input through KLT relation. The total symmetry among the n -particles of gravity amplitudes allows us to choose any leg to be soft leg. We take p_1 to be soft and solve $n-1, n$ as

$$\tilde{\lambda}_{n-1} = -\sum_{k=2}^{n-2} \frac{\langle n|k\rangle}{\langle n|n-1\rangle} \tilde{\lambda}_k - \epsilon \frac{\langle n|1\rangle}{\langle n|n-1\rangle} \tilde{\lambda}_1, \quad \tilde{\lambda}_n = -\sum_{k=2}^{n-2} \frac{\langle n-1|k\rangle}{\langle n-1|n\rangle} \tilde{\lambda}_k - \epsilon \frac{\langle n-1|1\rangle}{\langle n-1|n\rangle} \tilde{\lambda}_1. \quad [\text{Solve-pp-1}] \quad (4.1)$$

The choice of KLT formula: In section 2, we have reviewed various formulations of KLT relation. To make the discussion simpler, we should start with proper choice of KLT formula. Since the leading contribution from two gluon amplitudes is the order $\frac{1}{\epsilon^2} \times \frac{1}{\epsilon^2}$ while the leading contribution of graviton amplitude is $\frac{1}{\epsilon^3}$, we are better to have manifest ϵ -factor from kernel part. Furthermore, since we have solved $\tilde{\lambda}_{n-1}, \tilde{\lambda}_n$ in (4.1), it is more convenient to have formula as less related to p_{n-1}, p_n as possible. Taking these things into consideration, we use the general formula given by (2.1) with $j=2$

$$M_n = (-1)^{n+1} \sum_{t=2}^{n-2} \sum_{\sigma, \beta \in S_{n-4}} A_n(1, t, \sigma, n-1, n) \mathcal{S}[t|t]_{p_1} \mathcal{S}[\sigma|\beta]_{p_{n-1}} \tilde{A}_n(t, 1, n-1, \beta, n) \quad [\text{KLT-Box-13-2}] \quad (4.2)$$

In this form, $\mathcal{S}[t|t]_{p_1} \rightarrow \epsilon s_{1t}$, while the expansion of the other kernel $\mathcal{S}[\sigma|\beta]_{p_{n-1}}$ can be written as⁶

$$e^{+\epsilon \frac{\langle n|1\rangle}{\langle n|t\rangle} \tilde{\lambda}_1 \frac{d}{d\lambda_t}} \mathcal{S}[\sigma|\beta]_{p_{n-1}}. \quad [\text{Soft-kernel-2}] \quad (4.3)$$

⁶From the definition of kernel, the ϵ -expansion should be given by $e^{-\epsilon \frac{\langle n|1\rangle}{\langle n|n-1\rangle} \tilde{\lambda}_1 \frac{\partial}{\partial\lambda_{n-1}}} \mathcal{S}[\sigma|\beta]_{p_{n-1}}$. However, noticing that

$$\tilde{\lambda}_1 \frac{d}{d\lambda_t} \mathcal{S}[\sigma|\beta]_{p_{n-1}} = \tilde{\lambda}_1 \left(-\frac{\langle n|t\rangle}{\langle n|n-1\rangle} \right) \frac{\partial}{\partial\tilde{\lambda}_{n-1}} \mathcal{S}[\sigma|\beta]_{p_{n-1}}$$

where we have used the fact that $\tilde{\lambda}_s \frac{d}{d\lambda_t} \mathcal{S}[\sigma|\beta]_{p_{n-1}}$ does not contain momentum p_t , we obtain (4.3).

For convenience, we use (3.3) to write down the singular soft limit of two stripped amplitudes in (4.2) as

$$A_n^{(n-1,n)}(1, t, \sigma, n-1, n) \rightarrow \frac{1}{\epsilon^2} \frac{\langle n|t \rangle}{\langle n|1 \rangle \langle 1|t \rangle} A_{n-1}^{(n-1,n)}(t, \sigma, n-1, n) \\ + \frac{1}{\epsilon} \frac{\langle n|t \rangle}{\langle n|1 \rangle \langle 1|t \rangle} \left(\frac{\langle n|1 \rangle}{\langle n|t \rangle} \tilde{\lambda}_1 \frac{d}{d\tilde{\lambda}_t} + \frac{\langle t|1 \rangle}{\langle t|n \rangle} \tilde{\lambda}_1 \frac{d}{d\tilde{\lambda}_n} \right) A_{n-1}(t, \sigma, n-1, n), \quad [\text{My-At-soft}] \quad (4.4)$$

$$\tilde{A}_n^{(n-1,n)}(t, 1, n-1, \beta, n) \rightarrow \frac{1}{\epsilon^2} \frac{\langle t|n-1 \rangle}{\langle t|1 \rangle \langle 1|n-1 \rangle} \tilde{A}_n(t, n-1, \beta, n) \\ + \frac{1}{\epsilon} \frac{\langle t|n-1 \rangle}{\langle t|1 \rangle \langle 1|n-1 \rangle} \left(\frac{\langle t|1 \rangle}{\langle t|n-1 \rangle} \tilde{\lambda}_1 \frac{d}{d\tilde{\lambda}_{n-1}} + \frac{\langle n-1|1 \rangle}{\langle n-1|t \rangle} \tilde{\lambda}_1 \frac{d}{d\tilde{\lambda}_t} \right) \tilde{A}_n(t, n-1, \beta, n) \quad [\text{My-At-soft}] \quad (4.5)$$

In the remainder of this section, we discuss the soft behavior of gravity amplitudes by KLT relations order by order.

4.1 The leading order part

Substituting the leading part of color-ordered Yang-Mills amplitudes A , \tilde{A} (given by $\frac{1}{\epsilon^2}$ terms of (4.4), (4.5)) as well as the leading part of momentum kernel \mathcal{S} (given by the ϵ term of $\mathcal{S}[t|t]_{p_1} \mathcal{S}[\sigma|\beta]_{p_{n-1}}$) into the KLT expression (4.2), we get the leading part of gravity amplitude under soft limit

$$M_n = (-1)^{n+1} \sum_{t=2}^{n-2} \sum_{\sigma, \beta \in S_{n-4}} \frac{1}{\epsilon^2} \frac{\langle n|t \rangle}{\langle n|1 \rangle \langle 1|t \rangle} A_{n-1}^{(n-1,n)}(t, \sigma, n-1, n) \epsilon_{S_{1t}} \mathcal{S}[\sigma|\beta]_{p_{n-1}}^{\epsilon \rightarrow 0} \\ \frac{1}{\epsilon^2} \frac{\langle t|n-1 \rangle}{\langle t|1 \rangle \langle 1|n-1 \rangle} \tilde{A}_n^{(n-1,n)}(t, n-1, \beta, n) \\ = \frac{1}{\epsilon^3} (-1)^{n+1} \sum_{t=2}^{n-2} \frac{[t|1] \langle n|t \rangle \langle n-1|t \rangle}{\langle t|1 \rangle \langle n|1 \rangle \langle n-1|1 \rangle} \sum_{\sigma, \beta \in S_{n-4}} A_{n-1}^{(n-1,n)}(t, \sigma, n-1, n) \mathcal{S}[\sigma|\beta]_{p_{n-1}}^{\epsilon \rightarrow 0} \tilde{A}_n^{(n-1,n)}(t, n-1, \beta, n) \\ = \frac{1}{\epsilon^3} (-) \sum_{t=2}^{n-2} \frac{[t|1] \langle n|t \rangle \langle n-1|t \rangle}{\langle t|1 \rangle \langle n|1 \rangle \langle n-1|1 \rangle} M_{n-1}(2, \dots, n) \\ = \frac{1}{\epsilon^3} S_{GR}^{(0)} M_{n-1}(2, \dots, n) \quad (4.6)$$

where, on the third line, we have used the S_{n-3} -symmetric KLT relation (2.6) for $(n-1)$ -point amplitudes. The soft factor of gravity is nothing but the $S_{GR}^{(0)}$ defined in (3.1) with $x = n$ and $y = n-1$.

4.2 The subleading order part

Now let us study the subleading order of stripped gravity amplitudes under the soft limit. We will do it in three steps. In the first step, we act the $S_{GR}^{(1)}$ defined in (3.1) on the KLT expressions (2.6) of $(n-1)$ -point gravity amplitudes directly. In the second step, we collect contributions of the subleading part from color ordered Yang-Mills amplitudes and momentum kernel in (4.2). Finally, we compare the two expressions from first two steps to prove (check) the subleading order soft factor $S_{GR}^{(1)}$ of gravity amplitude.

4.2.1 The sub-leading part from direct acting of $S_{GR}^{(1)}$

We use the subleading soft factor given by (3.1)

$$S_{GR,(n-1)n}^{(1)} = - \sum_{i=2}^n \frac{[1|i] \langle n-1|i \rangle}{\langle 1|i \rangle \langle n-1|1 \rangle} \tilde{\lambda}_1 \frac{d}{d\tilde{\lambda}_i} = - \sum_{i=2}^{n-2} \frac{[1|i] \langle n-1|i \rangle}{\langle 1|i \rangle \langle n-1|1 \rangle} \tilde{\lambda}_1 \frac{d}{d\tilde{\lambda}_i} \quad [\text{MyKLT-direct-S14} \text{ (4.7)}]$$

where we have taken the gauge choice $x = y = n - 1$, thus $\frac{d}{d\tilde{\lambda}_{n-1}} = \frac{d}{d\tilde{\lambda}_n} = 0$. When acting it with the form (4.7) on M_{n-1} , for each i , we take different representation of M_{n-1} ⁷, i.e.,

$$\begin{aligned} S_{GR,(n-1)n}^{(1)} M_{n-1}(2, \dots, n) &= - \sum_{i=2}^{n-2} \frac{[1|i] \langle n-1|i \rangle}{\langle 1|i \rangle \langle n-1|1 \rangle} \tilde{\lambda}_1 \frac{d}{d\tilde{\lambda}_i} M_{n-1}(2, \dots, n) \\ &= - \sum_{i=2}^{n-2} \frac{[1|i] \langle n-1|i \rangle}{\langle 1|i \rangle \langle n-1|1 \rangle} \tilde{\lambda}_1 \frac{d}{d\tilde{\lambda}_i} \left[(-1)^n \sum_{\sigma, \beta \in S_{n-4}} A_{n-1}(i, \sigma, n-1, n) \mathcal{S}[\sigma|\beta]_{p_{n-1}} \tilde{A}_{n-1}(i, n-1, \beta, n) \right] \\ &= (-1)^{n+1} \sum_{i=2}^{n-2} \sum_{\sigma, \beta \in S_{n-4}} \frac{[1|i] \langle n-1|i \rangle}{\langle 1|i \rangle \langle n-1|1 \rangle} A_{n-1}(i, \sigma, n-1, n) \left(\tilde{\lambda}_1 \frac{d}{d\tilde{\lambda}_i} \mathcal{S}[\sigma|\beta]_{p_{n-1}} \right) \tilde{A}_{n-1}(i, n-1, \beta, n) \\ &+ (-1)^{n+1} \sum_{i=2}^{n-2} \sum_{\sigma, \beta \in S_{n-4}} \frac{[1|i] \langle n-1|i \rangle}{\langle 1|i \rangle \langle n-1|1 \rangle} \left(\tilde{\lambda}_1 \frac{d}{d\tilde{\lambda}_i} A_{n-1}(i, \sigma, n-1, n) \right) \mathcal{S}[\sigma|\beta]_{p_{n-1}} \tilde{A}_{n-1}(i, n-1, \beta, n) \\ &+ (-1)^{n+1} \sum_{i=2}^{n-2} \sum_{\sigma, \beta \in S_{n-4}} \frac{[1|i] \langle n-1|i \rangle}{\langle 1|i \rangle \langle n-1|1 \rangle} A_{n-1}(i, \sigma, n-1, n) \mathcal{S}[\sigma|\beta]_{p_{n-1}} \left(\tilde{\lambda}_1 \frac{d}{d\tilde{\lambda}_i} \tilde{A}_{n-1}(i, n-1, \beta, n) \right). \quad [\text{Direct-2}] \end{aligned} \quad (4.8)$$

4.2.2 The sub-leading order part from KLT relation

Now we collect the contributions of the subleading part from the KLT relation (4.2). There are three contributions at this order. The first term is to take kernel to second order of ϵ , while A, \tilde{A} are the first order (see (4.4) and (4.5)). This part is given by

$$\begin{aligned} T_1 &= (-1)^{n+1} \sum_{t=2}^{n-2} \sum_{\sigma, \beta \in S_{n-4}} \frac{[1|t] \langle n|t \rangle \langle n-1|t \rangle}{\langle 1|t \rangle \langle n|1 \rangle \langle n-1|1 \rangle} A_{n-1}(t, \sigma, n-1, n) \left(\frac{\langle n|1 \rangle}{\langle n|t \rangle} \tilde{\lambda}_1 \frac{d}{d\tilde{\lambda}_t} \mathcal{S}[\sigma|\beta]_{p_{n-1}} \right) \tilde{A}_{n-1}(t, n-1, \beta, n) \\ &= (-1)^{n+1} \sum_{t=2}^{n-2} \sum_{\sigma, \beta \in S_{n-4}} \frac{[1|t] \langle n-1|t \rangle}{\langle 1|t \rangle \langle n-1|1 \rangle} A_{n-1}(t, \sigma, n-1, n) \left(\tilde{\lambda}_1 \frac{d}{d\tilde{\lambda}_t} \mathcal{S}[\sigma|\beta]_{p_{n-1}} \right) \tilde{A}_{n-1}(t, n-1, \beta, n) \quad (4.9) \end{aligned}$$

For the second term, we keep the leading order of kernel and \tilde{A} while taking the subleading order of A , thus we have

$$T_2 = (-1)^{n+1} \sum_{t=2}^{n-2} \sum_{\sigma, \beta \in S_{n-4}} \frac{[1|t] \langle n|t \rangle \langle n-1|t \rangle}{\langle 1|t \rangle \langle n|1 \rangle \langle n-1|1 \rangle}$$

⁷It is worth to notice that although as a whole, we have the freedom to chose x, y for $S_{GR,(n-1)n}^{(1)}$, when we act it for different i and different part A, \tilde{A} in (4.8), we need to stick to a particular gauge choice.

$$\begin{aligned}
& \times \left[\left(\frac{\langle n|1\rangle}{\langle n|t\rangle} \tilde{\lambda}_1 \frac{d}{d\tilde{\lambda}_t} + \frac{\langle t|1\rangle}{\langle t|n\rangle} \tilde{\lambda}_1 \frac{d}{d\tilde{\lambda}_n} \right) A_{n-1}(t, \sigma, n-1, n) \right] \mathcal{S}[\sigma|\beta]_{p_{n-1}} \tilde{A}_n(t, n-1, \beta, n) \\
& = (-1)^{n+1} \sum_{t=2}^{n-2} \sum_{\sigma, \beta \in S_{n-4}} \frac{[1|t] \langle n-1|t\rangle}{\langle 1|t\rangle \langle n-1|1\rangle} \left(\tilde{\lambda}_1 \frac{d}{d\tilde{\lambda}_t} A_{n-1}(t, \sigma, n-1, n) \right) \mathcal{S}[\sigma|\beta]_{p_{n-1}} \left(\tilde{A}_n(t, n-1, \beta, n) \right),
\end{aligned} \tag{4.10}$$

where we have used the fact that $\frac{d}{d\tilde{\lambda}_n} A_{n-1}(t, \sigma, n-1, n) = 0$

For the third term, we keep the leading order of kernel and A while take the subleading order of \tilde{A} , thus we have

$$\begin{aligned}
T_3 & = (-1)^{n+1} \sum_{t=2}^{n-2} \sum_{\sigma, \beta \in S_{n-4}} \frac{[1|t] \langle n|t\rangle \langle n-1|t\rangle}{\langle 1|t\rangle \langle n|1\rangle \langle n-1|1\rangle} A_{n-1}(t, \sigma, n-1, n) \mathcal{S}[\sigma|\beta]_{p_{n-1}} \\
& \quad \left(\left\{ \frac{\langle t|1\rangle}{\langle t|n-1\rangle} \tilde{\lambda}_1 \frac{d}{d\tilde{\lambda}_{n-1}} + \frac{\langle n-1|1\rangle}{\langle n-1|t\rangle} \tilde{\lambda}_1 \frac{d}{d\tilde{\lambda}_t} \right\} \tilde{A}_n^{(n-1, n)}(t, n-1, \beta, n) \right) \\
& = (-1)^{n+1} \sum_{t=2}^{n-2} \sum_{\sigma, \beta \in S_{n-4}} \frac{[1|t] \langle n|t\rangle}{\langle 1|t\rangle \langle n|1\rangle} A_{n-1}(t, \sigma, n-1, n) \mathcal{S}[\sigma|\beta]_{p_{n-1}} \left(\tilde{\lambda}_1 \frac{d}{d\tilde{\lambda}_t} \tilde{A}_n^{(n-1, n)}(t, n-1, \beta, n) \right)
\end{aligned} \tag{4.11}$$

where again we have used the fact $\tilde{\lambda}_1 \frac{d}{d\tilde{\lambda}_{n-1}} \tilde{A}_n^{(n-1, n)}(t, n-1, \beta, n) = 0$.

4.2.3 Comparing sub-leading parts

Now we compare (4.8) with T_1, T_2, T_3 . It is easy to see when we identify $i = t$, we have

$$\begin{aligned}
\Delta & = S_{GR, (n-1)n}^{(1)} M_{n-1}(2, \dots, n) - T_1 - T_2 - T_3 \\
& = (-1)^{n+1} \sum_{t=2}^{n-2} \sum_{\sigma, \beta \in S_{n-4}} \frac{[1|t]}{\langle 1|t\rangle} \left(\frac{\langle n-1|t\rangle}{\langle n-1|1\rangle} - \frac{\langle n|t\rangle}{\langle n|1\rangle} \right) A_{n-1}(t, \sigma, n-1, n) \mathcal{S}[\sigma|\beta]_{p_{n-1}} \left(\tilde{\lambda}_1 \frac{d}{d\tilde{\lambda}_t} \tilde{A}_n^{(n-1, n)}(t, n-1, \beta, n) \right) \\
& = (-1)^{n+1} \sum_{t=2}^{n-2} \sum_{\sigma, \beta \in S_{n-4}} \frac{[1|t] \langle n|n-1\rangle}{\langle n-1|1\rangle \langle n|1\rangle} A_{n-1}(t, \sigma, n-1, n) \mathcal{S}[\sigma|\beta]_{p_{n-1}} \left(\tilde{\lambda}_1 \frac{d}{d\tilde{\lambda}_t} \tilde{A}_n^{(n-1, n)}(t, n-1, \beta, n) \right) \\
& = (-1)^{n+1} \sum_{t=2}^{n-2} \sum_{\sigma, \beta \in S_{n-4}} \frac{\tilde{\lambda}_1^{\dot{\alpha}} \tilde{\lambda}_1^{\dot{\beta}} \langle n|n-1\rangle}{\langle n-1|1\rangle \langle n|1\rangle} A_{n-1}(t, \sigma, n-1, n) \mathcal{S}[\sigma|\beta]_{p_{n-1}} \left(\tilde{\lambda}_{t, \dot{\alpha}} \frac{d}{d\tilde{\lambda}_t^{\dot{\beta}}} \tilde{A}_n^{(n-1, n)}(t, n-1, \beta, n) \right) \\
& = (-1)^{n+1} \sum_{t=2}^{n-2} \sum_{\sigma, \beta \in S_{n-4}} \frac{\tilde{\lambda}_1^{\dot{\alpha}} \tilde{\lambda}_1^{\dot{\beta}} \langle n|n-1\rangle}{\langle n-1|1\rangle \langle n|1\rangle} A_{n-1}(t, \sigma, n-1, n) \mathcal{S}[\sigma|\beta]_{p_{n-1}} \left(J_{t, \dot{\alpha}\dot{\beta}} \tilde{A}_n(t, n-1, \beta, n) \right) \quad \text{[Need-to-proof(4.12)]}
\end{aligned}$$

It is obviously that to prove (or check) the subleading soft factor $S_{GR, (n-1)n}^{(1)}$, we need to prove (or check) $\Delta = 0$. Before going to the detail, let us notice that in (4.12) only the anti-spinor part of angular momentum $J_{t, \dot{\alpha}\dot{\beta}}$ appears.

Now we present the idea of proof. In (4.12), for each t , we have used different BCJ-basis for color ordered partial amplitudes. Thus the first step is to translate various basis into a standard basis. In other words, we should do following transformation

$$\begin{aligned}
A_{n-1}(t, \sigma_t, n-1, n) &= \sum_{\sigma_{\tilde{t}} \in S_{n-4}} A_{n-1}(\tilde{t}, \sigma_{\tilde{t}}, n-1, n) \mathcal{D}[\tilde{t}, \sigma_{\tilde{t}}, n-1, n | t, \sigma_t, n-1, n] \\
\tilde{A}_{n-1}(t, n-1, \beta_t, n) &= \sum_{\beta_{\tilde{t}} \in S_{n-4}} \mathcal{C}[t, n-1, \beta_t, n | \tilde{t}, n-1, \beta_{\tilde{t}}, n] \tilde{A}_{n-1}(\tilde{t}, n-1, \beta_{\tilde{t}}, n). \quad [\text{minimal-basis}] \quad (4.13)
\end{aligned}$$

where we have used the σ_t to denote the permutations of $n-4$ -elements after deleting particles $1, n, n-1, t$. Inserting above transformation into the extra term (4.12), when we choose e.g., $\tilde{t} = 2$ in above equations, we obtain

$$\begin{aligned}
& (-1)^{n+1} \Delta \\
&= \sum_{\sigma_2, \beta_2 \in S_{n-4}} \frac{\tilde{\lambda}_1^{\dot{\alpha}} \tilde{\lambda}_1^{\dot{\beta}} \langle n | n-1 \rangle}{\langle n-1 | 1 \rangle \langle n | 1 \rangle} A_{n-1}(2, \sigma_2, n-1, n) \sum_{\tilde{t}=2}^{n-2} \sum_{\sigma_{\tilde{t}}, \beta_{\tilde{t}} \in S_{n-4}} \mathcal{D}[2, \sigma_2, n-1, n | \tilde{t}, \sigma_{\tilde{t}}, n-1, n] \mathcal{S}[\sigma_{\tilde{t}} | \beta_{\tilde{t}}]_{p_{n-1}} \\
&\quad J_{\tilde{t}, \dot{\alpha} \dot{\beta}} \left\{ \mathcal{C}[\tilde{t}, n-1, \beta_{\tilde{t}}, n | 2, n-1, \beta_2, n] \tilde{A}_{n-1}(2, n-1, \beta_2, n) \right\} \\
&= \sum_{\sigma_2, \beta_2 \in S_{n-4}} \frac{\tilde{\lambda}_1^{\dot{\alpha}} \tilde{\lambda}_1^{\dot{\beta}} \langle n | n-1 \rangle}{\langle n-1 | 1 \rangle \langle n | 1 \rangle} A_{n-1}(2, \sigma_2, n-1, n) \sum_{\tilde{t}=2}^{n-2} \sum_{\sigma_{\tilde{t}}, \beta_{\tilde{t}} \in S_{n-4}} \mathcal{D}[2, \sigma_2, n-1, n | \tilde{t}, \sigma_{\tilde{t}}, n-1, n] \mathcal{S}[\sigma_{\tilde{t}} | \beta_{\tilde{t}}]_{p_{n-1}} \\
&\quad \mathcal{C}[\tilde{t}, n-1, \beta_{\tilde{t}}, n | 2, n-1, \beta_2, n] \left\{ \tilde{J}_{\tilde{t}, \dot{\alpha} \dot{\beta}} A_{n-1}(2, n-1, \beta_2, n) \right\} \\
&+ \sum_{\sigma_2, \beta_2 \in S_{n-4}} \frac{\tilde{\lambda}_1^{\dot{\alpha}} \tilde{\lambda}_1^{\dot{\beta}} \langle n | n-1 \rangle}{\langle n-1 | 1 \rangle \langle n | 1 \rangle} A_{n-1}(2, \sigma_2, n-1, n) \sum_{\tilde{t}=2}^{n-2} \sum_{\sigma_{\tilde{t}}, \beta_{\tilde{t}} \in S_{n-4}} \mathcal{D}[2, \sigma_2, n-1, n | \tilde{t}, \sigma_{\tilde{t}}, n-1, n] \mathcal{S}[\sigma_{\tilde{t}} | \beta_{\tilde{t}}]_{p_{n-1}} \\
&\quad \left\{ J_{\tilde{t}, \dot{\alpha} \dot{\beta}} \mathcal{C}[\tilde{t}, n-1, \beta_{\tilde{t}}, n | 2, n-1, \beta_2, n] \right\} \tilde{A}_{n-1}(2, n-1, \beta_2, n). \quad [\text{Need-to-proof-2}] \quad (4.14)
\end{aligned}$$

For the first term in (4.14), if we have the following identity

$$\boxed{\sum_{\sigma_{\tilde{t}}, \beta_{\tilde{t}} \in S_{n-4}} \mathcal{D}[t, \sigma_t, n-1, n | \tilde{t}, \sigma_{\tilde{t}}, n-1, n] \mathcal{S}[\sigma_{\tilde{t}} | \beta_{\tilde{t}}]_{p_{n-1}} \mathcal{C}[\tilde{t}, n-1, \beta_{\tilde{t}}, n | t, n-1, \beta_t, n] = \mathcal{S}[\sigma_t | \beta_t]_{p_{n-1}}}, \quad [\text{KLT-equiv}] \quad (4.15)$$

the first term can be simplified as

$$\begin{aligned}
& \sum_{\sigma_2, \beta_2 \in S_{n-4}} \frac{\tilde{\lambda}_1^{\dot{\alpha}} \tilde{\lambda}_1^{\dot{\beta}} \langle n | n-1 \rangle}{\langle n-1 | 1 \rangle \langle n | 1 \rangle} A_{n-1}(2, \sigma_2, n-1, n) \sum_{\tilde{t}=2}^{n-2} \mathcal{S}[\sigma_2 | \beta_2]_{p_{n-1}} \left\{ J_{\tilde{t}, \dot{\alpha} \dot{\beta}} \tilde{A}_{n-1}(2, n-1, \beta_2, n) \right\} \\
&= \sum_{\sigma_2, \beta_2 \in S_{n-4}} \frac{\tilde{\lambda}_1^{\dot{\alpha}} \tilde{\lambda}_1^{\dot{\beta}} \langle n | n-1 \rangle}{\langle n-1 | 1 \rangle \langle n | 1 \rangle} A_{n-1}(2, \sigma_2, n-1, n) \mathcal{S}[\sigma_2 | \beta_2]_{p_{n-1}} \left\{ \left[\sum_{\tilde{t}=2}^{n-2} J_{\tilde{t}, \dot{\alpha} \dot{\beta}} \right] \tilde{A}_{n-1}(2, n-1, \beta_2, n) \right\} \\
&= 0, \quad (4.16)
\end{aligned}$$

where we have used angular momentum conservation

$$\begin{aligned}
& \tilde{\lambda}_1^{\dot{\alpha}} \tilde{\lambda}_1^{\dot{\beta}} \left\{ \sum_{\tilde{t}=2}^{n-2} J_{\tilde{t}, \dot{\alpha} \dot{\beta}} \right\} \left\{ \tilde{A}_{n-1}(2, n-1, \beta_2, n) \right\} = \tilde{\lambda}_1^{\dot{\alpha}} \tilde{\lambda}_1^{\dot{\beta}} \left\{ \sum_{\tilde{t}=2}^n J_{\tilde{t}, \dot{\alpha} \dot{\beta}} \right\} \left\{ \tilde{A}_{n-1}(2, n-1, \beta_2, n) \right\} \\
& = (-\tilde{\lambda}_1^{\dot{\alpha}} \tilde{\lambda}_1^{\dot{\beta}} J_{\tilde{t}=1, \dot{\alpha} \dot{\beta}}) \left\{ \tilde{A}_{n-1}(2, n-1, \beta_2, n) \right\} = 0.
\end{aligned} \tag{4.17}$$

For the second term in (4.14), if we have the following identity

$$0 = \sum_{\tilde{t}=2}^{n-2} \sum_{\sigma_{\tilde{t}}, \beta_{\tilde{t}} \in S_{n-4}} \mathcal{D}[t, \sigma_t, n-1, n | \tilde{t}, \sigma_{\tilde{t}}, n-1, n] \mathcal{S}[\sigma_{\tilde{t}} | \beta_{\tilde{t}}]_{p_{n-1}} J_{\tilde{t}, \dot{\alpha} \dot{\beta}} \left\{ \mathcal{C}[\tilde{t}, n-1, \beta_{\tilde{t}}, n | t, n-1, \beta_t, n] \right\}, \tag{4.18}^{[\text{non-trivial}]}$$

for arbitrary $t \in \{2, 3, \dots, n-2\}$ and related $\{\sigma_t, \beta_t\}$, the contribution vanishes also.

Identities (4.15) and (4.18) are the consistency requirement of the new soft graviton theorem and the old KLT formula. While the first identity can be understood from the changing of the basis (we will discuss it shortly), the second identity is very nontrivial. Currently, we do not have an analytic proof for them although in our few examples, we have checked them explicitly. We believe the knowledge of these two identities will tell us some important aspects of momentum kernel $\mathcal{S}[\alpha|\beta]$.

Now we present the physical understanding of the first identity (4.15). Noticing that we have many $(n-3)!$ symmetry KLT forms. They are equivalent to each other, but it is hard to see that from the angle of BCJ relation for color-ordered Yang-Mills theory. In other words, we have

$$\begin{aligned}
M_{n-1} &= \sum_{\sigma_t, \beta_t \in S_{n-4}} A_{n-1}(t, \sigma_t, n-1, n) \mathcal{S}[\sigma_t | \beta_t]_{p_{n-1}} \tilde{A}_{n-1}(t, n-1, \beta_t, n) \\
&= \sum_{\sigma_{\tilde{t}}, \beta_{\tilde{t}} \in S_{n-4}} A_{n-1}(\tilde{t}, \sigma_{\tilde{t}}, n-1, n) \mathcal{S}[\sigma_{\tilde{t}} | \beta_{\tilde{t}}]_{p_{n-1}} \tilde{A}_{n-1}(\tilde{t}, n-1, \beta_{\tilde{t}}, n)
\end{aligned} \tag{4.19}$$

where σ_t, β_t is the set of removing element t from $\{2, 3, \dots, n-2\}$. Plugging the transformation of basis (4.13) back, we have

$$\begin{aligned}
& \sum_{\sigma_{\tilde{t}}, \beta_{\tilde{t}} \in S_{n-4}} A_{n-1}(\tilde{t}, \sigma_{\tilde{t}}, n-1, n) \mathcal{S}[\sigma_{\tilde{t}} | \beta_{\tilde{t}}]_{p_{n-1}} \tilde{A}_{n-1}(\tilde{t}, n-1, \beta_{\tilde{t}}, n) \\
&= \sum_{\sigma_{\tilde{t}}, \beta_{\tilde{t}} \in S_{n-4}} \left\{ \sum_{\sigma_t \in S_{n-4}} A_{n-1}(t, \sigma_t, n-1, n) \mathcal{D}[t, \sigma_t, n-1, n | \tilde{t}, \sigma_{\tilde{t}}, n-1, n] \right\} \mathcal{S}[\sigma_{\tilde{t}} | \beta_{\tilde{t}}]_{p_{n-1}} \\
& \quad \left\{ \sum_{\beta_t \in S_{n-4}} \mathcal{C}[\tilde{t}, n-1, \beta_{\tilde{t}}, n | t, n-1, \beta_t, n] \tilde{A}_{n-1}(t, n-1, \beta_t, n) \right\} \\
&= \sum_{\sigma_t \in S_{n-4}} A_{n-1}(t, \sigma_t, n-1, n) \left\{ \sum_{\sigma_{\tilde{t}}, \beta_{\tilde{t}} \in S_{n-4}} \mathcal{D}[t, \sigma_t, n-1, n | \tilde{t}, \sigma_{\tilde{t}}, n-1, n] \mathcal{S}[\sigma_{\tilde{t}} | \beta_{\tilde{t}}]_{p_{n-1}} \mathcal{C}[\tilde{t}, n-1, \beta_{\tilde{t}}, n | t, n-1, \beta_t, n] \right\}
\end{aligned}$$

$$\tilde{A}_{n-1}(t, n-1, \beta_t, n) \tag{4.20}$$

Because the independence of the BCJ basis, we should obtain the identity (4.15).

4.3 The sub-sub-leading part from KLT relation

Now we consider the sub-sub-leading order. From the KLT formula, we have

$$\begin{aligned} & (\epsilon^{-2}A_{L,0} + \epsilon^{-1}A_{L,1} + \epsilon^0A_{L,2} + \dots)(\epsilon\mathcal{S}_0 + \epsilon^2\mathcal{S}_1 + \epsilon^3\mathcal{S}_2 + \dots)(\epsilon^{-2}A_{R,0} + \epsilon^{-1}A_{R,1} + \epsilon^0A_{R,2} + \dots) \\ &= \epsilon^{-3}A_{L,0}\mathcal{S}_0A_{R,0} + \epsilon^{-2}(A_{L,1}\mathcal{S}_0A_{R,0} + A_{L,0}\mathcal{S}_1A_{R,0} + A_{L,0}\mathcal{S}_0A_{R,1}) \\ &+ \epsilon^{-1}(A_{L,2}\mathcal{S}_0A_{R,0} + A_{L,0}\mathcal{S}_2A_{R,0} + A_{L,0}\mathcal{S}_0A_{R,2} + A_{L,1}\mathcal{S}_1A_{R,0} + A_{L,0}\mathcal{S}_1A_{R,1} + A_{L,1}\mathcal{S}_0A_{R,1}) + \dots \end{aligned} \tag{4.21}$$

Thus we see that to use this formula to study the sub-sub-leading singularity, we need to get the information of $\epsilon^0A_{L,2}$, which does not have the universal structure and has not been fully discussed.

5. Examples

Having the general frame in previous section, we will present a few examples to demonstrate our ideas. In this section, we will give examples of $n = 5, 6$ while the more complicated example of $n = 7$ will be given in the Appendix.

5.1 The case $n = 5$

Following our convention, in the stripped amplitude, $\tilde{\lambda}_4$ and $\tilde{\lambda}_5$ should be replaced by

$$\tilde{\lambda}_4 = - \sum_{k=2,3} \frac{\langle 5|k\rangle}{\langle 5|4\rangle} \tilde{\lambda}_k - \epsilon \frac{\langle 5|1\rangle}{\langle 5|4\rangle} \tilde{\lambda}_1, \quad \tilde{\lambda}_5 = - \sum_{k=2,3} \frac{\langle 4|k\rangle}{\langle 4|5\rangle} \tilde{\lambda}_k - \epsilon \frac{\langle 4|1\rangle}{\langle 4|5\rangle} \tilde{\lambda}_1. \tag{5.1}$$

In particular that $\frac{d}{d\tilde{\lambda}_4^\beta} \tilde{A} = \frac{d}{d\tilde{\lambda}_5^\beta} \tilde{A} = 0$, and therefore $J_{4\dot{\alpha}\dot{\beta}} \tilde{A} = J_{5\dot{\alpha}\dot{\beta}} \tilde{A} = 0$. At 5-points it is relatively straightforward to write down all of the terms in Δ as

$$\begin{aligned} \Delta_{n=5} &= \frac{\tilde{\lambda}_1^{\dot{\alpha}} \tilde{\lambda}_1^{\dot{\beta}} \langle 5|4\rangle}{\langle 4|1\rangle \langle 5|1\rangle} \left\{ A_4(2, 3, 4, 5) \mathcal{S}[3|3]_{p_4} \left(J_{2,\dot{\alpha}\dot{\beta}} \tilde{A}_4(2, 4, 3, 5) \right) + A_4(3, 2, 4, 5) \mathcal{S}[2|2]_{p_4} \left(J_{3,\dot{\alpha}\dot{\beta}} \tilde{A}_4(3, 4, 2, 5) \right) \right\} \\ &= \frac{\tilde{\lambda}_1^{\dot{\alpha}} \tilde{\lambda}_1^{\dot{\beta}} \langle 5|4\rangle}{\langle 4|1\rangle \langle 5|1\rangle} \left\{ A_4(2, 3, 4, 5) s_{34} \left(J_{2,\dot{\alpha}\dot{\beta}} \tilde{A}_4(2, 4, 3, 5) \right) + A_4(3, 2, 4, 5) s_{24} \left(J_{3,\dot{\alpha}\dot{\beta}} \tilde{A}_4(3, 4, 2, 5) \right) \right\}^{[\text{delta-5}]} \end{aligned} \tag{5.2}$$

Now we do the changing of basis, i.e., using the BCJ relation to write

$$\begin{aligned} A_4(3, 2, 4, 5) &= \frac{s_{34}}{s_{24}} A_4(2, 3, 4, 5) \\ \tilde{A}_4(3, 4, 2, 5) &= (-)^4 \tilde{A}_4(5, 2, 4, 3) = \tilde{A}_4(2, 4, 3, 5) \end{aligned} \tag{5.3}$$

Plugging them back we get

$$\Delta_{n=5} = \frac{\tilde{\lambda}_1^{\dot{\alpha}} \tilde{\lambda}_1^{\dot{\beta}} \langle 5|4\rangle}{\langle 4|1\rangle \langle 5|1\rangle} A_4(3, 2, 4, 5) s_{24} \left\{ \left(J_{3,\dot{\alpha}\dot{\beta}} + J_{2,\dot{\alpha}\dot{\beta}} \right) \tilde{A}_4(3, 4, 2, 5) \right\} = 0 \tag{5.4}$$

by angular momentum conservation $\sum_{i=2}^5 J_i \tilde{A} = 0$ (where $J_4 \tilde{A} = J_5 \tilde{A} = 0$ has been used). For this case, two identities (4.15) and (4.18) are trivial to check.

5.2 The case $n = 6$

For $n = 6$ the difference term $\Delta_{n=6}$ splits into three parts: $t = 2, 3$ and 4 ,

$$\Delta_{n=6} = \Delta_{n=6}^{t=2} + \Delta_{n=6}^{t=3} + \Delta_{n=6}^{t=4} \quad (5.5)$$

where we have solved

$$\tilde{\lambda}_5 = - \sum_{k=2,3,4} \frac{\langle 6|k\rangle}{\langle 6|5\rangle} \tilde{\lambda}_k - \epsilon \frac{\langle 6|1\rangle}{\langle 6|5\rangle} \tilde{\lambda}_1, \quad \tilde{\lambda}_6 = - \sum_{k=2,3,4} \frac{\langle 5|k\rangle}{\langle 5|6\rangle} \tilde{\lambda}_k - \epsilon \frac{\langle 5|1\rangle}{\langle 5|6\rangle} \tilde{\lambda}_1. \quad [6\text{pt-mom-conserv.}] \quad (5.6)$$

For simplicity in the following discussion we suppress a common factor $(-)^{n+1} \frac{\langle n|n-1\rangle}{\langle n-1|1\rangle \langle n|1\rangle} \tilde{\lambda}_1^\alpha \tilde{\lambda}_1^\beta$ from the difference terms, thus we can write

$$\begin{aligned} \Delta_{n=6}^{t=2} &= A_5(2, 3, 4, 5, 6) \mathcal{S}[3, 4|3, 4]_{p_5} (J_2 \tilde{A}_5(2, 5, 3, 4, 6)) + A_5(2, 3, 4, 5, 6) \mathcal{S}[3, 4|4, 3]_{p_5} (J_2 \tilde{A}_5(2, 5, 4, 3, 6)) \\ &\quad + A_5(2, 4, 3, 5, 6) \mathcal{S}[4, 3|3, 4]_{p_5} (J_2 \tilde{A}_5(2, 5, 3, 4, 6)) + A_5(2, 4, 3, 5, 6) \mathcal{S}[4, 3|4, 3]_{p_5} (J_2 \tilde{A}_5(2, 5, 4, 3, 6)) \\ \Delta_{n=6}^{t=3} &= A_5(3, 2, 4, 5, 6) \mathcal{S}[2, 4|2, 4]_{p_5} (J_3 \tilde{A}_5(3, 5, 2, 4, 6)) + A_5(3, 2, 4, 5, 6) \mathcal{S}[2, 4|4, 2]_{p_5} (J_3 \tilde{A}_5(3, 5, 4, 2, 6)) \\ &\quad + A_5(3, 4, 2, 5, 6) \mathcal{S}[4, 2|2, 4]_{p_5} (J_3 \tilde{A}_5(3, 5, 2, 4, 6)) + A_5(3, 4, 2, 5, 6) \mathcal{S}[4, 2|4, 2]_{p_5} (J_3 \tilde{A}_5(3, 5, 4, 2, 6)) \\ \Delta_{n=6}^{t=4} &= A_5(4, 2, 3, 5, 6) \mathcal{S}[2, 3|2, 3]_{p_5} (J_4 \tilde{A}_5(4, 5, 2, 3, 6)) + A_5(4, 2, 3, 5, 6) \mathcal{S}[2, 3|3, 2]_{p_5} (J_4 \tilde{A}_5(4, 5, 3, 2, 6)) \\ &\quad + A_5(4, 3, 2, 5, 6) \mathcal{S}[3, 2|2, 3]_{p_5} (J_4 \tilde{A}_5(4, 5, 2, 3, 6)) + A_5(4, 3, 2, 5, 6) \mathcal{S}[3, 2|3, 2]_{p_5} (J_4 \tilde{A}_5(4, 5, 3, 2, 6)) \end{aligned} \quad (5.7)$$

Now we translate all amplitudes A into the basis $\{A(6, 2, 4, 3, 5), A(6, 2, 3, 4, 5)\}$

$$\begin{aligned} A_5(6, 4, 2, 3, 5) &= \frac{(s_{43} + s_{45})A_5(6, 2, 4, 3, 5) + s_{45}A_5(6, 2, 3, 4, 5)}{s_{46}} \\ A_5(6, 3, 2, 4, 5) &= \frac{(s_{34} + s_{35})A_5(6, 2, 3, 4, 5) + s_{35}A_5(6, 2, 4, 3, 5)}{s_{36}} \\ A_5(6, 4, 3, 2, 5) &= \frac{-s_{24}s_{35}A_5(6, 2, 4, 3, 5) - s_{45}(s_{25} + s_{23})A_5(6, 2, 3, 4, 5)}{s_{46}s_{25}} \\ A_5(6, 3, 4, 2, 5) &= \frac{-s_{23}s_{45}A_5(6, 2, 3, 4, 5) - s_{35}(s_{25} + s_{24})A_5(6, 2, 4, 3, 5)}{s_{36}s_{25}} \end{aligned} \quad (5.8)$$

and all amplitudes \tilde{A}_5 into the basis $\{\tilde{A}_5(2, 5, 3, 4, 6), \tilde{A}_5(2, 5, 4, 3, 6)\}$

$$\begin{aligned} \tilde{A}_5(3, 5, 2, 4, 6) &= \frac{-\tilde{A}_5(2, 5, 3, 4, 6)(s_{45} + s_{43}) - \tilde{A}_5(2, 5, 4, 3, 6)s_{45}}{s_{24}} \\ \tilde{A}_5(4, 5, 2, 3, 6) &= \frac{-\tilde{A}_5(2, 5, 4, 3, 6)(s_{35} + s_{43}) - \tilde{A}_5(2, 5, 3, 4, 6)s_{35}}{s_{23}} \end{aligned}$$

$$\begin{aligned}
\tilde{A}_5(3, 5, 4, 2, 6) &= \frac{-(s_{43} + s_{46})\tilde{A}_5(2, 5, 4, 3, 6) - s_{46}\tilde{A}_5(2, 5, 3, 4, 6)}{s_{24}} \\
\tilde{A}_5(4, 5, 3, 2, 6) &= \frac{-(s_{43} + s_{36})\tilde{A}_5(2, 5, 3, 4, 6) - s_{36}\tilde{A}_5(2, 5, 4, 3, 6)}{s_{23}}
\end{aligned} \tag{5.9}$$

Putting it back with some calculation we have

$$\begin{aligned}
\Delta_{n=6}^{t=3} &= A_5(2, 3, 4, 5, 6) \left\{ -s_{45}(s_{23} + s_{25})(J_{3,\dot{\alpha}\dot{\beta}} \frac{-\tilde{A}_5(2, 5, 3, 4, 6)(s_{45} + s_{43}) - \tilde{A}_5(2, 5, 4, 3, 6)s_{45}}{s_{24}}) \right. \\
&\quad \left. + s_{45}s_{26}(J_{3,\dot{\alpha}\dot{\beta}} \frac{-(s_{43} + s_{46})\tilde{A}_5(2, 5, 4, 3, 6) - s_{46}\tilde{A}_5(2, 5, 3, 4, 6)}{s_{24}}) \right\} \\
&\quad + A_5(2, 4, 3, 5, 6) \left\{ -s_{35}s_{24}(J_{3,\dot{\alpha}\dot{\beta}} \frac{-\tilde{A}_5(2, 5, 3, 4, 6)(s_{45} + s_{43}) - \tilde{A}_5(2, 5, 4, 3, 6)s_{45}}{s_{24}}) \right\}
\end{aligned} \tag{5.10}$$

Further simplification by using (notice that $J_{3,\dot{\alpha}\dot{\beta}}s_{24} = 0$)

$$\begin{aligned}
(s_{23} + s_{25})(J_{3,\dot{\alpha}\dot{\beta}}(s_{45} + s_{43})) - s_{26}(J_{3,\dot{\alpha}\dot{\beta}}s_{46}) &= s_{24}(J_{3,\dot{\alpha}\dot{\beta}}s_{46}) \\
(s_{23} + s_{25})(J_{3,\dot{\alpha}\dot{\beta}}s_{45}) - s_{26}(J_{3,\dot{\alpha}\dot{\beta}}(s_{43} + s_{46})) &= -s_{24}(J_{3,\dot{\alpha}\dot{\beta}}s_{45})
\end{aligned} \tag{5.11}$$

leads

$$\begin{aligned}
\Delta_{n=6}^{t=3} &= A_5(2, 3, 4, 5, 6) \left\{ \mathcal{S}[3, 4|3, 4]_{p_5}(J_{3,\dot{\alpha}\dot{\beta}}\tilde{A}_5(2, 5, 3, 4, 6)) + \mathcal{S}[3, 4|4, 3]_{p_5}(J_{3,\dot{\alpha}\dot{\beta}}\tilde{A}_5(2, 5, 4, 3, 6)) \right. \\
&\quad \left. + s_{45}(J_{3,\dot{\alpha}\dot{\beta}}s_{46})\tilde{A}_5(2, 5, 3, 4, 6) - s_{45}\tilde{A}_5(2, 5, 4, 3, 6)(J_{3,\dot{\alpha}\dot{\beta}}s_{45}) \right\} \\
&\quad + A_5(2, 4, 3, 5, 6) \left\{ \mathcal{S}[4, 3|3, 4]_{p_5}(J_{3,\dot{\alpha}\dot{\beta}}\tilde{A}_5(2, 5, 3, 4, 6)) + \mathcal{S}[4, 3|4, 3]_{p_5}(J_{3,\dot{\alpha}\dot{\beta}}\tilde{A}_5(2, 5, 4, 3, 6)) \right. \\
&\quad \left. - s_{35}\tilde{A}_5(2, 5, 3, 4, 6)(J_{3,\dot{\alpha}\dot{\beta}}s_{46}) + s_{35}\tilde{A}_5(2, 5, 4, 3, 6)(J_{3,\dot{\alpha}\dot{\beta}}s_{45}) \right\}
\end{aligned} \tag{5.12}$$

Notice that part of them (i.e., the part with J acting only on \tilde{A}) is exactly the same as $\Delta_{n=6}^{t=2}$ except the $J_{2,\dot{\alpha}\dot{\beta}}$ is replaced by $J_{3,\dot{\alpha}\dot{\beta}}$. It is nothing, but the explicit checking the identity (4.15) with $t = 2, \tilde{t} = 3$.

Doing similar calculation we found

$$\begin{aligned}
\Delta_{n=6}^{t=4} &= A_5(2, 3, 4, 5, 6) \left\{ \mathcal{S}[3, 4|3, 4]_{p_5}(J_{4,\dot{\alpha}\dot{\beta}}\tilde{A}_5(2, 5, 3, 4, 6)) + \mathcal{S}[3, 4|4, 3]_{p_5}(J_{4,\dot{\alpha}\dot{\beta}}\tilde{A}_5(2, 5, 4, 3, 6)) \right. \\
&\quad \left. + s_{45}(J_{4,\dot{\alpha}\dot{\beta}}s_{35})\tilde{A}_5(2, 5, 3, 4, 6) + s_{45}\tilde{A}_5(2, 5, 4, 3, 6)(J_{4,\dot{\alpha}\dot{\beta}}(s_{34} + s_{35})) \right\} \\
&\quad + A_5(2, 4, 3, 5, 6) \left\{ \mathcal{S}[4, 3|3, 4]_{p_5}(J_{4,\dot{\alpha}\dot{\beta}}\tilde{A}_5(2, 5, 3, 4, 6)) + \mathcal{S}[4, 3|4, 3]_{p_5}(J_{4,\dot{\alpha}\dot{\beta}}\tilde{A}_5(2, 5, 4, 3, 6)) \right. \\
&\quad \left. - s_{35}\tilde{A}_5(2, 5, 3, 4, 6)(J_{4,\dot{\alpha}\dot{\beta}}s_{35}) + s_{35}\tilde{A}_5(2, 5, 4, 3, 6)(J_{4,\dot{\alpha}\dot{\beta}}s_{36}) \right\}
\end{aligned} \tag{5.13}$$

where again the identity (4.15) with $t = 2, \tilde{t} = 4$ has been checked. Thus when we sum up three terms $\Delta_{n=6}^{t=2}, \Delta_{n=6}^{t=3}, \Delta_{n=6}^{t=4}$, the part with J acting directly on \tilde{A} vanishes by angular momentum conservation and

we are left with

$$\begin{aligned}
R = & A_5(2, 3, 4, 5, 6) \left\{ +s_{45}(J_{3,\dot{\alpha}\dot{\beta}}s_{46})\tilde{A}_5(2, 5, 3, 4, 6) - s_{45}\tilde{A}_5(2, 5, 4, 3, 6)(J_{3,\dot{\alpha}\dot{\beta}}s_{45}) \right. \\
& \left. +s_{45}(J_{4,\dot{\alpha}\dot{\beta}}s_{35})\tilde{A}_5(2, 5, 3, 4, 6) - s_{45}\tilde{A}_5(2, 5, 4, 3, 6)(J_{4,\dot{\alpha}\dot{\beta}}s_{36}) \right\} \\
& + A_5(2, 4, 3, 5, 6) \left\{ -s_{35}\tilde{A}_5(2, 5, 3, 4, 6)(J_{3,\dot{\alpha}\dot{\beta}}s_{46}) + s_{35}\tilde{A}_5(2, 5, 4, 3, 6)(J_{3,\dot{\alpha}\dot{\beta}}s_{45}) \right. \\
& \left. -s_{35}\tilde{A}_5(2, 5, 3, 4, 6)(J_{4,\dot{\alpha}\dot{\beta}}s_{35}) + s_{35}\tilde{A}_5(2, 5, 4, 3, 6)(J_{4,\dot{\alpha}\dot{\beta}}s_{36}) \right\} \tag{5.14}
\end{aligned}$$

where J acts only on s_{ij} . Using

$$\begin{aligned}
J_{3,\dot{\alpha}\dot{\beta}}s_{i5} &= -\langle 5|i\rangle \frac{\langle 6|3\rangle}{\langle 6|5\rangle} \tilde{\lambda}_{3,\dot{\alpha}} \tilde{\lambda}_{i,\dot{\beta}}, & J_{3,\dot{\alpha}\dot{\beta}}s_{i6} &= -\langle 6|i\rangle \frac{\langle 5|3\rangle}{\langle 5|6\rangle} \tilde{\lambda}_{3,\dot{\alpha}} \tilde{\lambda}_{i,\dot{\beta}}, & J_{3,\dot{\alpha}\dot{\beta}}s_{i3} &= +\langle 3|i\rangle \tilde{\lambda}_{3,\dot{\alpha}} \tilde{\lambda}_{i,\dot{\beta}}, & i &= 2, 4 \\
J_{4,\dot{\alpha}\dot{\beta}}s_{i5} &= -\langle 5|i\rangle \frac{\langle 6|4\rangle}{\langle 6|5\rangle} \tilde{\lambda}_{4,\dot{\alpha}} \tilde{\lambda}_{i,\dot{\beta}}, & J_{4,\dot{\alpha}\dot{\beta}}s_{i6} &= -\langle 6|i\rangle \frac{\langle 5|4\rangle}{\langle 5|6\rangle} \tilde{\lambda}_{4,\dot{\alpha}} \tilde{\lambda}_{i,\dot{\beta}}, & J_{4,\dot{\alpha}\dot{\beta}}s_{i4} &= +\langle 4|i\rangle \tilde{\lambda}_{4,\dot{\alpha}} \tilde{\lambda}_{i,\dot{\beta}}, & i &= 2, 3
\end{aligned}$$

we see immediately that $R = 0$. In other words, we have explicitly checked the second identity (4.18) for the special case.

6. Conclusion

In this paper, we studied the new soft graviton theorem from the angle of KLT relation. We have demonstrated that how the new soft gluon theorem are glued together by KLT formula to produce the corresponding soft theorem for gravity. In the process, two important identities (4.15) and (4.18) has been observed.

There are a lot of open questions deserve to be investigated. First, the two identities need an analytic proof. Secondly, the sub-sub-leading soft factor in KLT relation should be understood. Although at this order, contributions from non-universal soft part of color ordered Yang-Mills amplitudes appear, we guess that their effects will be canceled out by nice property of momentum kernel \mathcal{S} . It will be fascinating to see how it happens. Thirdly, in this paper, we have focused on the 4D, it will be interesting to discuss it in general dimension since KLT formula holds in general dimension. Finally, there are also other general formulas for gravity amplitudes (such as these given in [34, 35, 36]) and it will be nice to see how the new soft graviton theorem makes its appearance.

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A. Example with $n = 7$

In this appendix we verify that identities (4.15) and (4.18) are holding at $n = 7$. Our strategy used in previous examples applies to 7-points, although the complexity involved increases considerably. As in the previous examples, we choose to work in a convenient minimum basis $\tilde{A}(2, 6, \beta_2, 7), A(2, \sigma_2, 6, 7)$ (Here we use A instead of A_6 for short), i.e., do the following transformation with $t = 3, 4, 5$:

$$\begin{aligned}\tilde{A}(t, 6, \beta_t, 7) &= \sum_{\beta_t \in S_3} \mathcal{C}[t, 6, \beta_t, 7|2, 6, \beta_2, 7] \tilde{A}(2, 6, \beta_2, 7), \quad [n=7-A1] \\ A(t, \sigma_t, 6, 7) &= \sum_{\sigma_t \in S_3} A(2, \sigma_2, 6, 7) \mathcal{D}[2, \sigma_2, 6, 7|t, \sigma, 6, 7].\end{aligned}\tag{A.1}$$

Our task then amounts to showing that, for both identities, terms associated with each independent product of basis amplitudes $A\tilde{A}$ match accordingly for both sides of the equations (4.15) and (4.18). In the discussion below we focus on terms containing $\tilde{A}(2, 6, 3, 4, 5, 7)$, namely when $\beta_2 = \{3, 4, 5\}$. The rest of the coefficients follow similar argument up to permutations of $\{3, 4, 5\}$. In principle it is straightforward to work out all translation coefficients \mathcal{C}, \mathcal{D} and check if the identities are holding. However we can perform the calculation in a slightly more organized manner. In particular note that common factors are quite often shared between different translation coefficients.

For the purpose of demonstration let us consider translating a specific amplitude $\tilde{A}(3, 6, 2, 4, 5, 7)$ into minimum basis. This can be done by first expressing the amplitude in the $\tilde{A}(2, \dots, 7)$ Kleiss-Klein (KK) basis that fixes legs 2 and 7 at both ends, and then subsequently translating to the $\tilde{A}(2, 6, \dots, 7)$ minimum basis of interest where legs 6 and 2 are adjacent:

$$\begin{aligned}\tilde{A}(3, 6, 2, 4, 5, 7) &= \tilde{A}(2, 4, 5, 6, 3, 7) + \tilde{A}(2, 4, 6, 5, 3, 7) + \tilde{A}(2, 4, 6, 3, 5, 7) + \tilde{A}(2, 6, 4, 5, 3, 7) \\ &\quad + \tilde{A}(2, 6, 4, 3, 5, 7) + \tilde{A}(2, 6, 3, 4, 5, 7) \\ &= \left(1 - \frac{(s_{42} + s_{46} + s_{43})}{s_{42}} + E[45, 3|345]\right) \tilde{A}(2, 6, 3, 4, 5, 7) \\ &\quad + \dots \left(\text{terms not contributing to } \tilde{A}(2, 6, 3, 4, 5, 7)\right),\end{aligned}\tag{A.2}$$

where in the third line we used BCJ relation to remove the ill-favored leg 4 between 2 and 6 in the next to adjacent amplitude $\tilde{A}(2, 4, 6, 5, 3, 7)$, and we introduced the shorthand notation $E[45, 3|345]$ to denote the next-to-next-to adjacent expansion coefficient,

$$\tilde{A}(2, \{4, 5\}, 6, \{3\}, 7) = \sum_{\sigma} E[45, 3|\sigma] \tilde{A}(2, 6, \sigma, 7).\tag{A.3}$$

The coefficient $E[45, 3|345]$ can be determined from simultaneous equations consisting of BCJ relations, yielding

$$E[45, 3|345] = \frac{(-1)}{s_{42}s_{52} - (s_{42} + s_{45})(s_{52} + s_{54})} \left[- (s_{42} + s_{45} + s_{46} + s_{43})(s_{52} + s_{56} + s_{53} + s_{54}) \right. \\ \left. + \frac{(s_{42} + s_{45})(s_{52} + s_{54} + s_{56} + s_{53})(s_{42} + s_{46} + s_{43})}{s_{42}} \right]. \quad (\text{A.4})$$

All translation coefficients can be determined via similar procedures. Explicitly we have, for the $t = 3$ sector,

$$\mathcal{C}[3, 6, 2, 4, 5, 7|2, 6, 3, 4, 5, 7] = 1 - \frac{(s_{42} + s_{46} + s_{43})}{s_{42}} + E[45, 3] \quad (\text{A.5})$$

$$\mathcal{C}[3, 6, 2, 5, 4, 7|2, 6, 3, 4, 5, 7] = - \frac{(s_{52} + s_{56} + s_{53} + s_{54})}{s_{52}} + E[54, 3]$$

$$\mathcal{C}[3, 6, 4, 2, 5, 7|2, 6, 3, 4, 5, 7] = \frac{(s_{42} + s_{46} + s_{43})}{s_{42}} - E[45, 3] - E[54, 3]$$

$$\mathcal{C}[3, 6, 4, 5, 2, 7|2, 6, 3, 4, 5, 7] = E[54, 3]$$

$$\mathcal{C}[3, 6, 5, 2, 4, 7|2, 6, 3, 4, 5, 7] = \frac{(s_{52} + s_{56} + s_{53} + s_{54})}{s_{52}} - E[45, 3] - E[54, 3]$$

$$\mathcal{C}[3, 6, 5, 4, 2, 7|2, 6, 3, 4, 5, 7] = E[45, 3]. \quad (\text{A.6})$$

For $t = 4$ we have

$$\mathcal{C}[4, 6, 2, 3, 5, 7|2, 6, 3, 4, 5, 7] = 1 - \frac{(s_{32} + s_{36})}{s_{32}} + E[35, 4] \quad (\text{A.7})$$

$$\mathcal{C}[4, 6, 2, 5, 3, 7|2, 6, 3, 4, 5, 7] = - \frac{(s_{52} + s_{56} + s_{53} + s_{54})}{s_{52}} + E[53, 4]$$

$$\mathcal{C}[4, 6, 3, 2, 5, 7|2, 6, 3, 4, 5, 7] = \frac{(s_{32} + s_{36})}{s_{32}} - E[35, 4] - E[53, 4]$$

$$\mathcal{C}[4, 6, 3, 5, 2, 7|2, 6, 3, 4, 5, 7] = E[53, 4]$$

$$\mathcal{C}[4, 6, 5, 2, 3, 7|2, 6, 3, 4, 5, 7] = \frac{(s_{52} + s_{56} + s_{53} + s_{54})}{s_{52}} - E[35, 4] - E[53, 4]$$

$$\mathcal{C}[4, 6, 5, 3, 2, 7|2, 6, 3, 4, 5, 7] = E[35, 4],$$

and similarly for $t = 5$,

$$\mathcal{C}[5, 6, 2, 3, 4, 7|2, 6, 3, 4, 5, 7] = 1 - \frac{(s_{32} + s_{36})}{s_{32}} + E[34, 5] \quad (\text{A.8})$$

$$\mathcal{C}[5, 6, 2, 4, 3, 7|2, 6, 3, 4, 5, 7] = - \frac{(s_{42} + s_{46} + s_{43})}{s_{42}} + E[43, 5]$$

$$\mathcal{C}[5, 6, 3, 2, 4, 7|2, 6, 3, 4, 5, 7] = \frac{(s_{32} + s_{36})}{s_{32}} - E[34, 5] - E[43, 5] \quad (\text{A.9})$$

$$\mathcal{C} [5, 6, 3, 4, 2, 7|2, 6, 3, 4, 5, 7] = E [43, 5] \quad (\text{A.10})$$

$$\mathcal{C} [5, 6, 4, 2, 3, 7|2, 6, 3, 4, 5, 7] = \frac{(s_{42} + s_{46} + s_{43})}{s_{42}} - E [34, 5] - E [43, 5] \quad (\text{A.11})$$

$$\mathcal{C} [5, 6, 4, 3, 2, 7|2, 6, 3, 4, 5, 7] = E [34, 5], \quad (\text{A.12})$$

whereas the next-to-next-to adjacent expansion coefficients are given by

$$E [54, 3] = \frac{(-1)}{s_{52}s_{42} - (s_{52} + s_{54})(s_{42} + s_{45})} \left[- (s_{52} + s_{54} + s_{56} + s_{53})(s_{42} + s_{46} + s_{43}) \right. \\ \left. + \frac{(s_{52} + s_{54})(s_{42} + s_{45} + s_{46} + s_{43})(s_{52} + s_{56} + s_{53} + s_{54})}{s_{52}} \right] \quad (\text{A.13})$$

$$E [35, 4] = \frac{(-1)}{s_{32}s_{52} - (s_{32} + s_{35})(s_{52} + s_{53})} \left[- (s_{32} + s_{35} + s_{36})(s_{52} + s_{56} + s_{53} + s_{54}) \right. \\ \left. + \frac{(s_{32} + s_{35})(s_{52} + s_{53} + s_{56} + s_{54})(s_{32} + s_{36})}{s_{32}} \right] \quad (\text{A.14})$$

$$E [53, 4] = \frac{(-1)}{s_{52}s_{32} - (s_{52} + s_{53})(s_{32} + s_{35})} \left[- (s_{52} + s_{53} + s_{56} + s_{54})(s_{32} + s_{36}) \right. \\ \left. + \frac{(s_{52} + s_{53})(s_{32} + s_{35} + s_{36})(s_{52} + s_{56} + s_{53} + s_{54})}{s_{52}} \right] \quad (\text{A.15})$$

$$E [34, 5] = \frac{(-1)}{s_{32}s_{42} - (s_{32} + s_{34})(s_{42} + s_{43})} \left[- (s_{32} + s_{34} + s_{36})(s_{42} + s_{46} + s_{43}) \right. \\ \left. + \frac{(s_{32} + s_{34})(s_{42} + s_{43} + s_{46})(s_{32} + s_{36})}{s_{32}} \right] \quad (\text{A.16})$$

$$E [43, 5] = \frac{(-1)}{s_{42}s_{32} - (s_{42} + s_{43})(s_{32} + s_{34})} \left[- (s_{42} + s_{43} + s_{46})(s_{32} + s_{36}) \right. \\ \left. + \frac{(s_{42} + s_{43})(s_{32} + s_{34} + s_{36})(s_{42} + s_{46} + s_{43})}{s_{42}} \right] \quad (\text{A.17})$$

Identity (4.15)

Let us first verify identity (4.15) for the case when $\beta_2 = \{345\}$, or equivalently that

$$\sum_{\sigma_{\tilde{t}}, \beta_{\tilde{t}}} A(\tilde{t}, \sigma_{\tilde{t}}, 67) \mathcal{S} [\sigma_{\tilde{t}} | \beta_{\tilde{t}}] \mathcal{C} [\tilde{t}, 6, \beta_{\tilde{t}}, 7] = \sum_{\sigma_2 \in \text{perm}\{345\}} A(2, \sigma_2, 67) \mathcal{S} [\sigma_2 | 345]_6 \quad (\text{A.18})$$

for each \tilde{t} . To keep the derivation simple we introduce the following shorthand notation for repeatedly occurring factors

$$T_{\tilde{t}}(\beta_{\tilde{t}}) = \sum_{\sigma_{\tilde{t}}} A(\tilde{t}, \sigma_{\tilde{t}}, 67) \mathcal{S} [\sigma_{\tilde{t}} | \beta_{\tilde{t}}]. \quad (\text{A.19})$$

so that for example when $\tilde{t} = 5$, equation (A.18) reads

$$\sum_{\beta_5 \in \text{perm}\{234\}} T_5(\beta_5) \mathcal{C} [5, 6, \beta_5, 7] = T_2(345). \quad (\text{A.20})$$

Substituting the explicit expressions for translation coefficients \mathcal{C} s, the left hand side of the above equation becomes

$$\begin{aligned}
& T_5(234) + (-T_5(234) + T_5(324)) \frac{s_{32} + s_{36}}{s_{32}} \\
& + (-T_5(243) + T_5(423)) \frac{s_{42} + s_{46} + s_{43}}{s_{42}} \\
& + (T_5(234) - T_5(324) - T_5(423) + T_5(432)) E[34, 5] \\
& + (T_5(243) - T_5(324) + T_5(342) - T_5(423)) E[43, 5].
\end{aligned} \tag{A.21}$$

With a little bit more effort, we find that the left hand side of (A.20) boils down to the following linear combination of amplitudes.

$$\begin{aligned}
& -s_{36}s_{46}(s_{56} + s_{54} + s_{53} + s_{52}) A(523467) \\
& -s_{36}(s_{34} + s_{46})(s_{56} + s_{54} + s_{53} + s_{52}) A(524367).
\end{aligned} \tag{A.22}$$

On the other hand the right hand side of (A.20) reads

$$\begin{aligned}
T_2(345) &= s_{36}s_{46}s_{56}A(234567) + s_{36}s_{46}(s_{46} + s_{56})A(235467) + s_{36}s_{46}(s_{53} + s_{54} + s_{56})A(253467) \\
&+ s_{36}(s_{43} + s_{46})s_{56}A(243567) + s_{36}(s_{43} + s_{46})(s_{56} + s_{53})A(245367) \\
&+ s_{36}(s_{43} + s_{46})(s_{53} + s_{54} + s_{56})A(254367),
\end{aligned} \tag{A.23}$$

We see that the first line of (A.22) matches the sum of the first three terms of equation (A.23), and similarly the second line of (A.22) matches the sum of the last three terms of (A.23) because of BCJ relation, thereby proving the identity (A.20). The situations when $\tilde{t} = 3$ and 4 can be proved in a likewise manner.

Identity (4.18)

At 7-points the difference term $\Delta_{n=7}$ splits into four parts, $\Delta_{n=7} = \sum_{t=2,3,4,5} \Delta_{n=7}^t$, where

$$\Delta_{n=7}^t = \sum_{\sigma, \beta \in S_3} A(t, \sigma, 6, 7) \mathcal{S}[\sigma|\beta]_6 J_t \tilde{A}(t, 6, \beta, 7) \tag{A.24}$$

Substituting the above expressions into equation (A.24) and collecting terms, we find as in the previous examples that terms where angular momentum operate on basis amplitudes \tilde{A} add up to zero because of angular momentum conservation $\sum_t J_t \tilde{A}(2, 6, 3, 4, 5, 7) = 0$, leaving us with the collection of terms that J_t operate on expansion coefficients \mathcal{C} , which are functions of kinematic variables. Contributions from the three respective sectors are given by

$$\begin{aligned}
\Delta_{t=3} &= (-T_3(245) + T_3(425)) J_3 \left(\frac{s_{42} + s_{46} + s_{43}}{s_{42}} \right) + (-T_3(254) + T_3(524)) J_3 \left(\frac{s_{52} + s_{56} + s_{53} + s_{54}}{s_{52}} \right) \\
&+ (T_3(245) - T_3(425) - T_3(524) + T_3(542)) J_3 (E[45, 3])
\end{aligned}$$

$$+ (T_3(254) - T_3(425) + T_3(452) - T_3(524)) J_3 (E [54, 3]), \quad (\text{A.25})$$

$$\begin{aligned} \Delta_{t=4} &= (-T_3(235) + T_3(325)) J_3 \left(\frac{s_{32} + s_{36}}{s_{32}} \right) + (-T_3(253) + T_3(523)) J_3 \left(\frac{s_{52} + s_{56} + s_{53} + s_{54}}{s_{52}} \right) \\ &+ (T_3(235) - T_3(325) - T_3(523) + T_3(532)) J_3 (E [35, 4]) \\ &+ (T_3(253) - T_3(325) + T_3(4352) - T_3(523)) J_3 (E [53, 4]), \end{aligned} \quad (\text{A.26})$$

$$\begin{aligned} \Delta_{t=5} &= (-T_3(234) + T_3(324)) J_3 \left(\frac{s_{32} + s_{36}}{s_{32}} \right) + (-T_3(243) + T_3(423)) J_3 \left(\frac{s_{42} + s_{46} + s_{43}}{s_{42}} \right) \\ &+ (T_3(234) - T_3(324) - T_3(423) + T_3(432)) J_3 (E [34, 5]) \\ &+ (T_3(243) - T_3(324) + T_3(342) - T_3(423)) J_3 (E [43, 5]), \end{aligned} \quad (\text{A.27})$$

Generically the operation of J_t on kinematic variables must fall into one of the following categories:

- $t = 3$,

$$J_{3 \dot{\alpha} \dot{\beta}} s_{i6} = \tilde{\lambda}_{3(\dot{\alpha} \tilde{\lambda}_{i \dot{\beta}})} (-) \frac{\langle i6 \rangle \langle 73 \rangle}{\langle 76 \rangle}, \quad i = 2, 4, 5 \quad (\text{A.28})$$

$$J_{3 \dot{\alpha} \dot{\beta}} s_{i7} = \tilde{\lambda}_{3(\dot{\alpha} \tilde{\lambda}_{i \dot{\beta}})} (-) \frac{\langle i7 \rangle \langle 63 \rangle}{\langle 67 \rangle}$$

$$J_{3 \dot{\alpha} \dot{\beta}} s_{i3} = \tilde{\lambda}_{3(\dot{\alpha} \tilde{\lambda}_{i \dot{\beta}})} \langle i3 \rangle \quad (\text{A.29})$$

$$J_{3 \dot{\alpha} \dot{\beta}} s_{i i'} = 0, \quad i, i' = 2, 4, 5$$

- $t = 4$,

$$J_{4 \dot{\alpha} \dot{\beta}} s_{i6} = \tilde{\lambda}_{4(\dot{\alpha} \tilde{\lambda}_{i \dot{\beta}})} (-) \frac{\langle i6 \rangle \langle 74 \rangle}{\langle 76 \rangle}, \quad i = 3, 4, 5 \quad (\text{A.30})$$

$$J_{4 \dot{\alpha} \dot{\beta}} s_{i7} = \tilde{\lambda}_{4(\dot{\alpha} \tilde{\lambda}_{i \dot{\beta}})} (-) \frac{\langle i7 \rangle \langle 64 \rangle}{\langle 67 \rangle}$$

$$J_{4 \dot{\alpha} \dot{\beta}} s_{i4} = \tilde{\lambda}_{4(\dot{\alpha} \tilde{\lambda}_{i \dot{\beta}})} \langle i4 \rangle$$

$$J_{4 \dot{\alpha} \dot{\beta}} s_{i i'} = 0, \quad i, i' = 3, 4, 5$$

- $t = 5$,

$$J_{5 \dot{\alpha} \dot{\beta}} s_{i6} = \tilde{\lambda}_{5(\dot{\alpha} \tilde{\lambda}_{i \dot{\beta}})} (-) \frac{\langle i6 \rangle \langle 75 \rangle}{\langle 76 \rangle}, \quad i = 2, 4, 5 \quad (\text{A.31})$$

$$J_{5 \dot{\alpha} \dot{\beta}} s_{i7} = \tilde{\lambda}_{5(\dot{\alpha} \tilde{\lambda}_{i \dot{\beta}})} (-) \frac{\langle i7 \rangle \langle 65 \rangle}{\langle 67 \rangle}$$

$$\begin{aligned}
J_{5\dot{\alpha}\dot{\beta}}s_{i3} &= \tilde{\lambda}_{5(\dot{\alpha}}\tilde{\lambda}_{i\dot{\beta})}\langle i5\rangle \\
J_{5\dot{\alpha}\dot{\beta}}s_{ii'} &= 0, \quad i, i' = 2, 4, 5
\end{aligned}$$

Suppose if we are interested in checking terms carrying $\tilde{\lambda}_{3(\dot{\alpha}}\tilde{\lambda}_{4\dot{\beta})}$. Before we commence an explicit calculation, note that because all of the \mathcal{C} s do not depend explicitly on leg 7, from the list above such a term can only be produced through $J_3(s_{46})$, $J_3(s_{43})$, $J_4(s_{36})$, $J_4(s_{34})$, which allows us to ignore the $t = 5$ sector entirely. Additionally since s_{34} happen to be absent from the $t = 4$ translation coefficient \mathcal{C} s, this leaves only $J_3(s_{46})$, $J_3(s_{43})$, $J_4(s_{36})$. Considering the explicit forms given by equations (A.28), (A.29) and (A.30) we further note that (again) because of the absence of the leg 7 dependence in all \mathcal{C} s, the contributions from $J_3(s_{46})$, $J_3(s_{43})$, $J_4(s_{36})$ together can only cancel through Jacobi identity $\langle 43\rangle + \frac{\langle 73\rangle\langle 64\rangle}{\langle 76\rangle} + \frac{\langle 74\rangle\langle 36\rangle}{\langle 76\rangle} = 0$. For that to happen, the contribution associated with $J_3(s_{46})$, $J_3(s_{43})$, $J_4(s_{36})$ must be exactly in the ratio $1 : 1 : -1$, in other words they must add up to

$$J_3(s_{46})X + J_3(s_{43})X + J_4(s_{36})(-X) = 0 \quad (\text{A.32})$$

for some factor X . In the following discussion we shall see that indeed this is the case.

First we note that it is relatively easy to confirm that the ratio between the contributions from $J_3(s_{46})$ and $J_3(s_{43})$ is $1 : 1$. This can be seen by observing that the kinematic factors s_{46} and s_{43} always show up together through the combination $s_{46} + s_{43}$ in all of the translation coefficients \mathcal{C} in the $t = 3$ sector (see equations from (A.5) to (A.6) as well as (A.25)). The only part of the argument that requires explicit calculation is the ratio between $J_3(s_{46})$ and $J_4(s_{36})$. For the purpose of discussion let us tentatively call them respectively as X and Y . From equation (A.25) and the definition of $E[45, 3]$ and $E[54, 3]$, the contribution associated with $J_3(s_{46})$ reads

$$\begin{aligned}
X &= \frac{1}{s_{42}s_{52}(s_{45} + s_{42} + s_{52})} [s_{52}(s_{45} + s_{42} + s_{52})(-T_3(245) + T_3(425)) \\
&\quad + s_{52}(s_{52} + s_{56} + s_{53} + s_{54})(T_3(245) - T_3(425) - T_3(524) + T_3(542)) \\
&\quad + s_{42}(s_{52} + s_{56} + s_{53} + s_{54})(T_3(254) - T_3(425) + T_3(452) - T_3(524))] \\
&= [s_{36}s_{56}A(4, 2, 3, 5, 6, 7) + s_{36}(s_{35} + s_{56})A(4, 2, 5, 3, 6, 7) \\
&\quad - s_{56}(s_{25} + s_{26} + s_{56} + s_{35} + s_{45})A(4, 3, 2, 5, 6, 7) + s_{26}(s_{35} + s_{45})A(4, 3, 5, 2, 6, 7) \\
&\quad - s_{36}s_{45}A(4, 5, 2, 3, 6, 7) + s_{26}s_{45}A(4, 5, 3, 2, 6, 7)] \quad (\text{A.33})
\end{aligned}$$

and similarly,

$$\begin{aligned}
Y &= \frac{1}{s_{32}s_{52}(s_{52} + s_{32} + s_{35})} [s_{52}(s_{52} + s_{32} + s_{35})(-T_4(235) + T_4(325)) \\
&\quad + s_{32}(s_{52} + s_{53} + s_{54} + s_{56})(T_4(253) - T_4(325) + T_4(352) - T_4(523)) \\
&\quad + s_{52}(s_{52} + s_{53} + s_{54} + s_{56})(T_4(235) - T_4(325) - T_4(523) + T_4(532))]
\end{aligned}$$

$$\begin{aligned}
&= [s_{36}s_{56}A(4, 2, 3, 5, 6, 7) + s_{36}(s_{35} + s_{56})A(4, 2, 5, 3, 6, 7) \\
&\quad - s_{56}(s_{25} + s_{26} + s_{56} + s_{35} + s_{45})A(4, 3, 2, 5, 6, 7) + s_{26}(s_{35} + s_{45})A(4, 3, 5, 2, 6, 7) \\
&\quad - s_{36}s_{45}A(4, 5, 2, 3, 6, 7) + s_{26}s_{45}A(4, 5, 3, 2, 6, 7)] \tag{A.34}
\end{aligned}$$

Now that we have the explicit formulas of the $J_3(s_{46})$ and $J_4(s_{36})$ term contributions, it is evident from (A.33) and (A.34) that they are related by an exchange of legs 3 and 4, $Y = X|_{3 \leftrightarrow 4}$. Therefore to prove $X = -Y$ it suffices to show that Y is antisymmetric with respect to indices 3 and 4. This antisymmetric structure will become manifest after some nontrivial manipulations, which we perform in the following.

First of all note that BCJ relation allows us to write

$$\begin{aligned}
&s_{36}s_{56}A(4, 2, 3, 5, 6, 7) + s_{36}(s_{35} + s_{56})A(4, 2, 5, 3, 6, 7) \\
&= -s_{36}(s_{52} + s_{53} + s_{56})A(4, 5, 2, 3, 6, 7) - s_{36}(s_{52} + s_{53} + s_{56} + s_{54})A(4, 2, 3, 6, 7, 5) \tag{A.35}
\end{aligned}$$

and

$$\begin{aligned}
&s_{26}(s_{35} + s_{45})A(4, 3, 5, 2, 6, 7) + s_{26}s_{45}A(4, 5, 3, 2, 6, 7) \\
&= -s_{26}(s_{35} + s_{45} + s_{25})A(4, 3, 2, 5, 6, 7) - s_{26}(s_{35} + s_{45} + s_{25} + s_{65})A(4, 3, 2, 6, 5, 7). \tag{A.36}
\end{aligned}$$

Plugging the above two identities into the expression for Y , we have

$$\begin{aligned}
Y &= -s_{36}(s_{52} + s_{53} + s_{56} + s_{54})[A(4, 5, 2, 3, 6, 7) + A(4, 2, 3, 6, 7, 5)] \\
&\quad - [s_{26}(s_{35} + s_{45} + s_{25}) + s_{56}(s_{25} + s_{26} + s_{56} + s_{35} + s_{45})]A(4, 3, 2, 5, 6, 7) \\
&\quad - s_{26}(s_{35} + s_{45} + s_{25} + s_{65})A(4, 3, 2, 6, 5, 7) \\
&= -(s_{52} + s_{53} + s_{56} + s_{54}) \\
&\quad \times [s_{36}A(4, 5, 2, 3, 6, 7) + s_{36}A(4, 2, 3, 6, 7, 5) + (s_{26} + s_{56})A(4, 3, 2, 5, 6, 7) + s_{26}A(4, 3, 2, 6, 5, 7)] \\
&= s_{57}[s_{36}A(4, 5, 2, 3, 6, 7) + s_{36}A(4, 2, 3, 6, 7, 5) + (s_{26} + s_{56})A(4, 3, 2, 5, 6, 7) + s_{26}A(4, 3, 2, 6, 5, 7)] \tag{A.37}
\end{aligned}$$

Further using BCJ relation identifies the sum of last two terms above with

$$\begin{aligned}
&(s_{26} + s_{56})A(4, 3, 2, 5, 6, 7) + s_{26}A(4, 3, 2, 6, 5, 7) \\
&= -(s_{26} + s_{56} + s_{76})A(4, 3, 2, 5, 7, 6) - (s_{26} + s_{56} + s_{76} + s_{46})A(4, 6, 3, 2, 5, 7) \\
&= (s_{36} + s_{46})A(4, 3, 2, 5, 7, 6) + s_{36}A(4, 6, 3, 2, 5, 7) \tag{A.38}
\end{aligned}$$

Therefore Y simplifies as

$$Y = s_{57}s_{36}[A(4, 5, 2, 3, 6, 7) + A(4, 2, 3, 6, 7, 5) + A(4, 3, 2, 5, 7, 6) + A(4, 6, 3, 2, 5, 7)]$$

$$\begin{aligned}
& +s_{57}s_{46}A(4, 3, 2, 5, 7, 6) \\
& = s_{57} [s_{46}A(4, 3, 2, 5, 7, 6) - s_{36}A(3, 4, 2, 5, 7, 6)]
\end{aligned} \tag{A.39}$$

where we used $U(1)$ decoupling identity to substitute the summation in the first line with a single amplitude. The final simplified formula of Y is manifestly antisymmetric under the exchange of indices 3 and 4, and we conclude that $X + Y = 0$ as claimed.

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